

AnyBody 8

NEW FEATURES AND MODELS

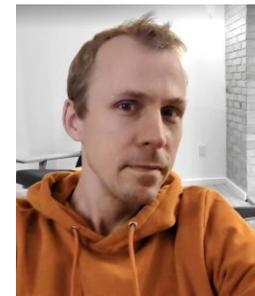
NEW
ANY
BODY

Topics

- New AnyBody 8
- New model repository (AMMR 3)
- Full thoracic models and public AMMR 4 on GitHub
- Questions...

Presenter

Morten Enemark Lund
Engineer
AnyBody Technology

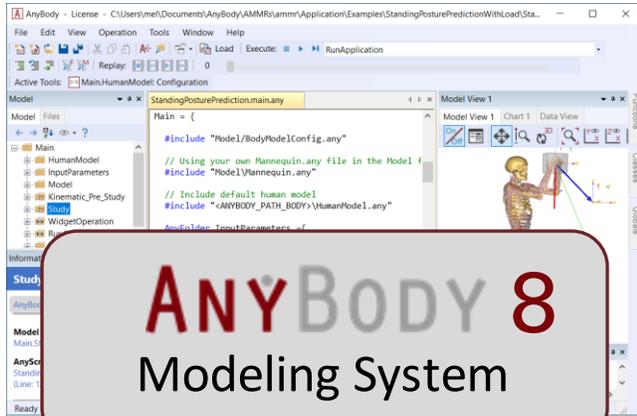


Panellist

Kristoffer Iversen
Head of Sales
AnyBody Technology

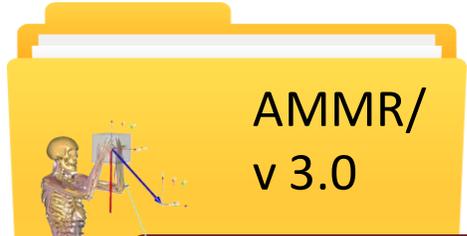


New Release: AnyBody 8



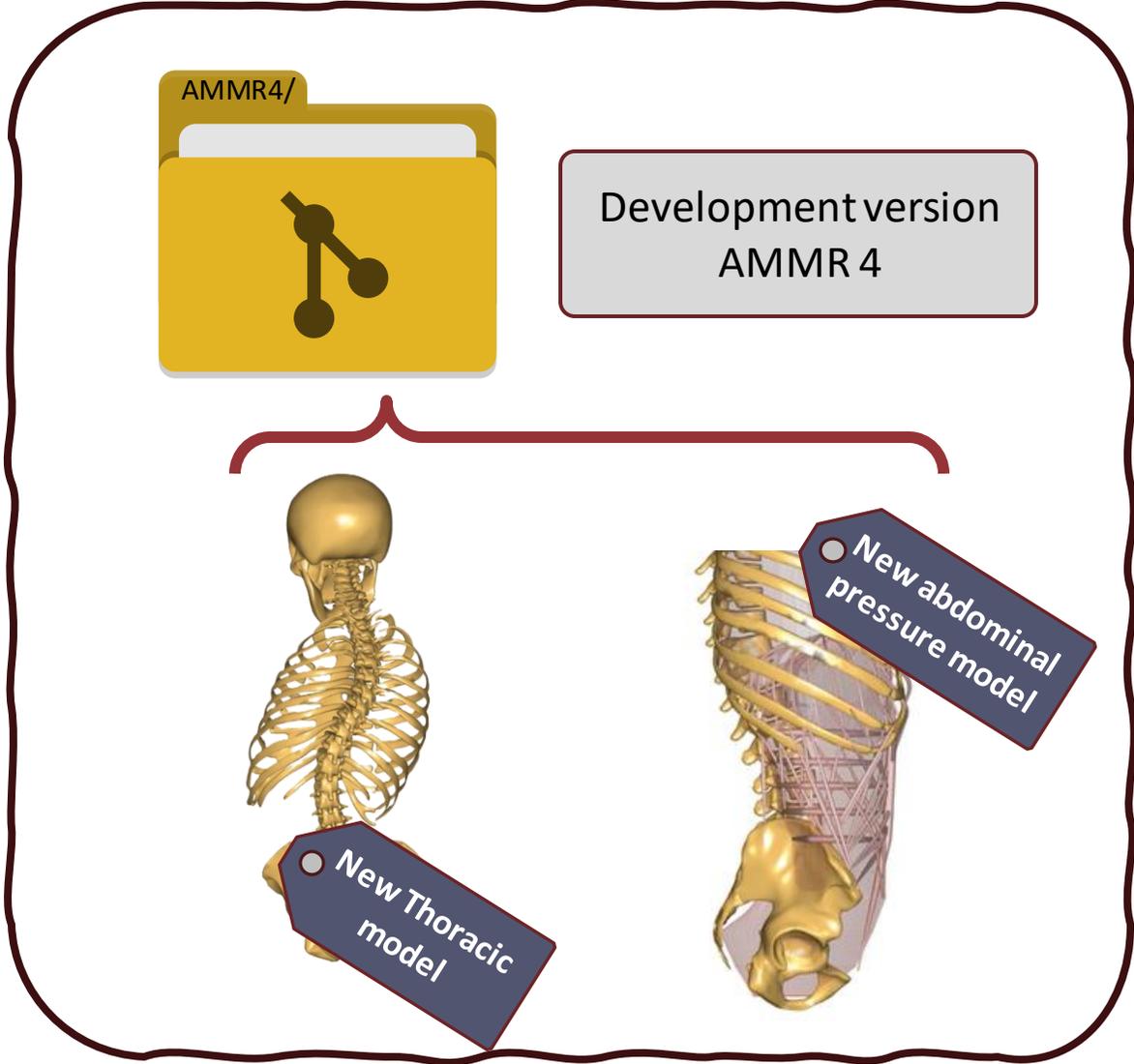
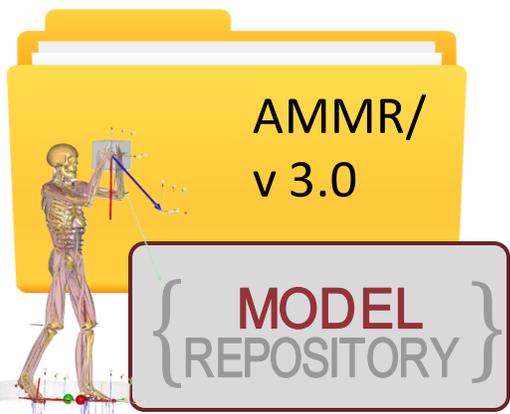
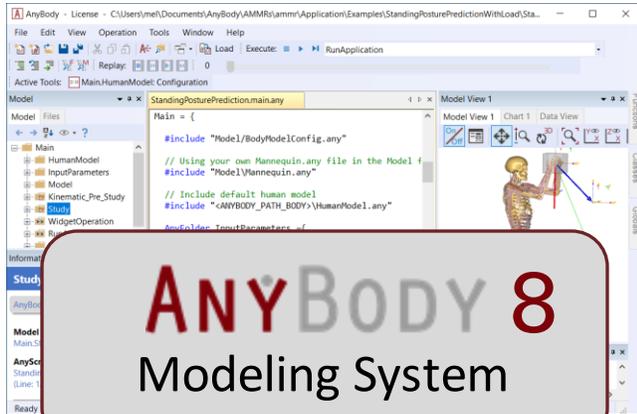
ANYBODY 8
Modeling System

Version 8.0.1

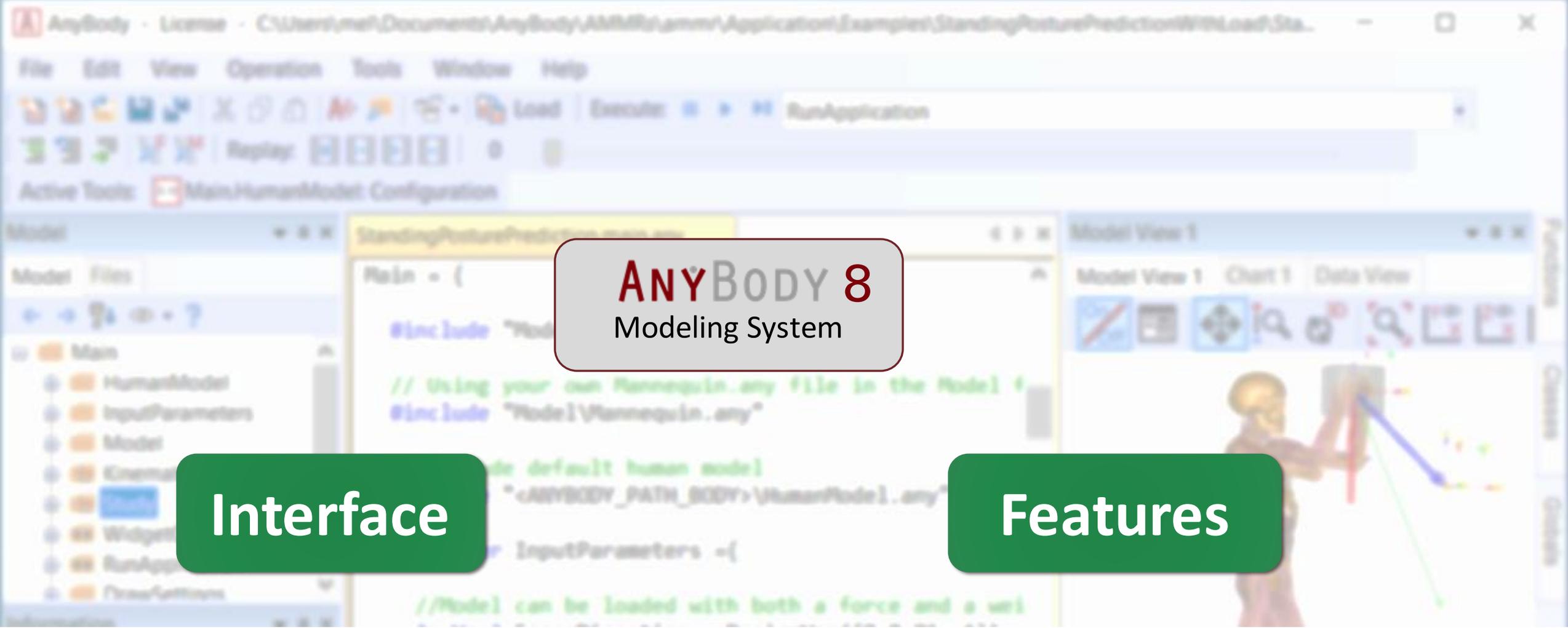


{
MODEL
REPOSITORY
}

New Release:



Online resources: github.com/anybody



ANYBODY 8
Modeling System

Interface

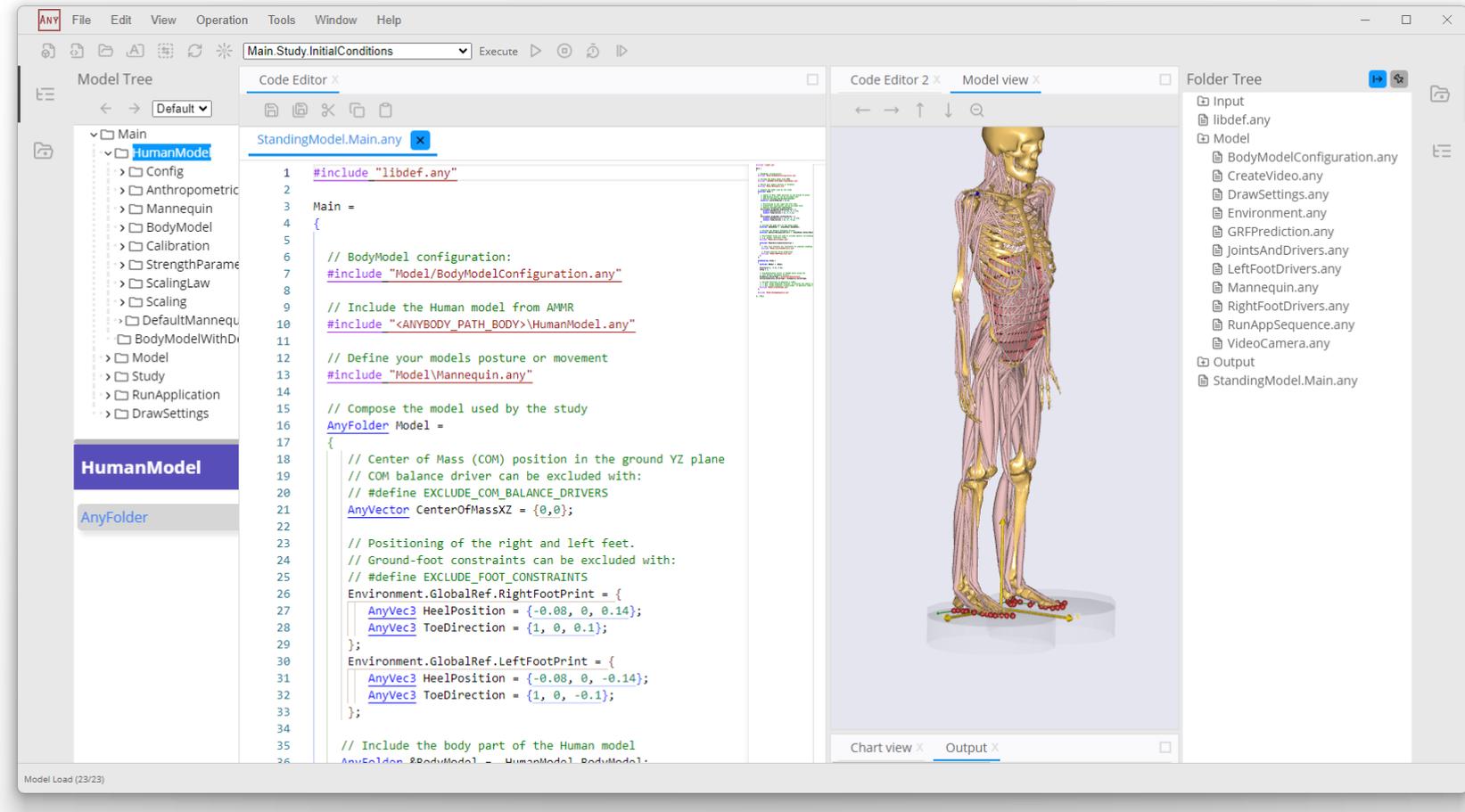
Features

AnyBody Modeling System

✦ Highlights in Version 8

User Interface - Highlights

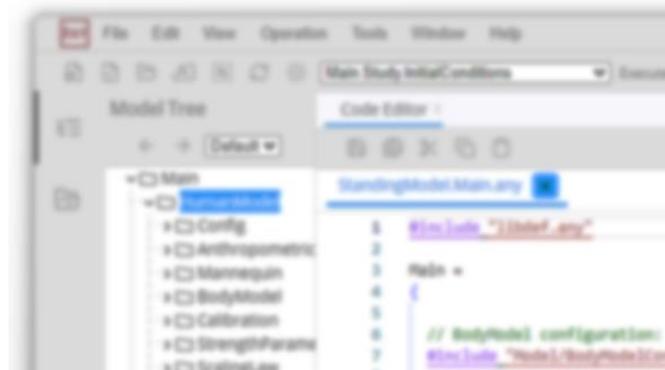
Only minor GUI changes



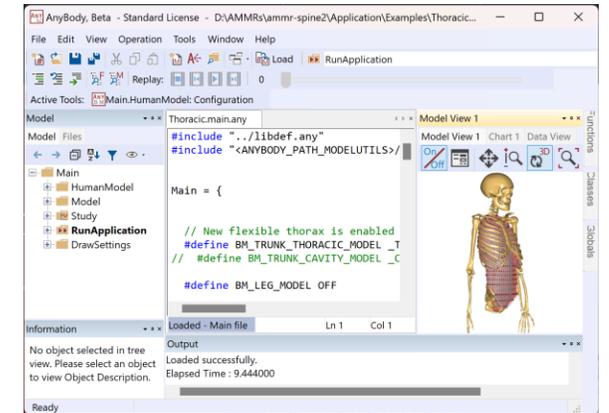
Teaser: New user interface in AnyBody 9

User Interface - Highlights

Only minor GUI changes

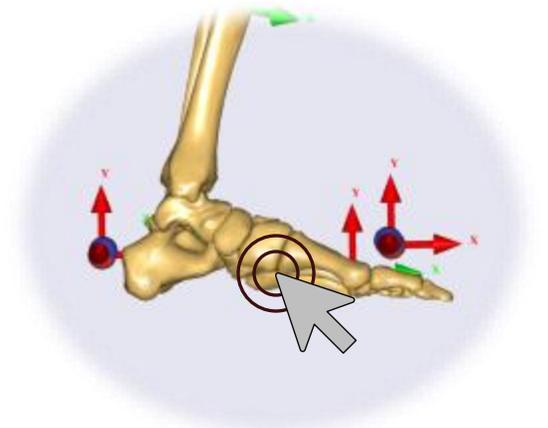
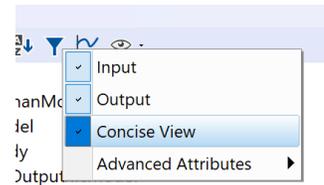
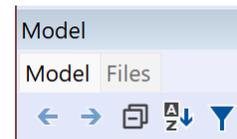
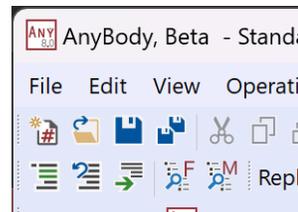


Teaser: New user interface in AnyBody 9



AnyBody 8 looks mostly the same

A few new buttons:



New Model view Interactions:

- CTRL+DoubleClick: Center view
- Shift+DoubleClick: Zoom and center

User Interface - Highlights

Only minor GUI changes

AnyScript

✦ Trailing commas in lists

✦ Class template imports

- Trailing commas now allowed in AnyScript

```
AnyString MyList = {  
    "elem1",  
    "elem2",  
    "elem3",  
};
```

In vectors,
matrices
and lists

```
AnyString Segments = arccat(  
    {"Humerus", "Ulna", "Radius"},  
    {"Scapula", "Clavicula"},  
);
```

In function
arguments

- New features for Class templates
 - No longer restricted to outside `Main={` scope

```
#include "MyModelTemplates.any"
```

```
MyModelTemplate Model( ) = {  
    // ...  
};
```

- Much easier to reuse code with class templates

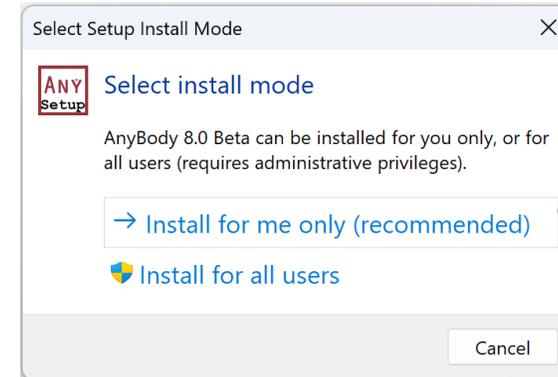
User Interface - Highlights

Only minor GUI changes

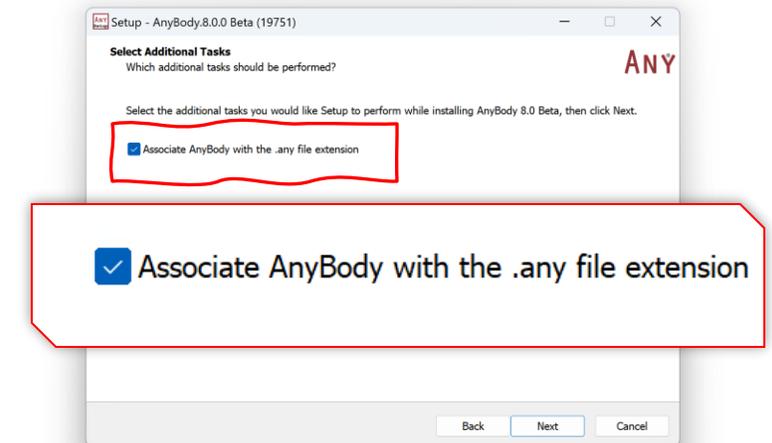
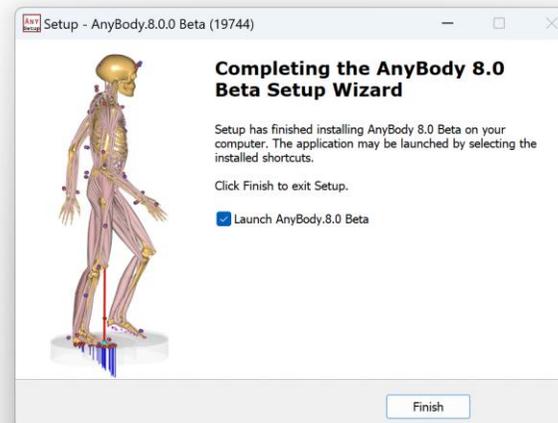
AnyScript

 **New Installer**


AnyBodySetup.8.0.1.exe

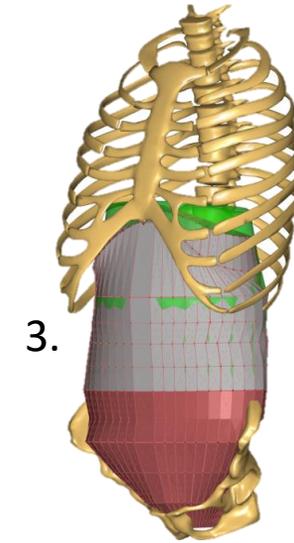


-  **Much faster install/uninstall**
-  **Silent installations**



New features in AnyBody 8

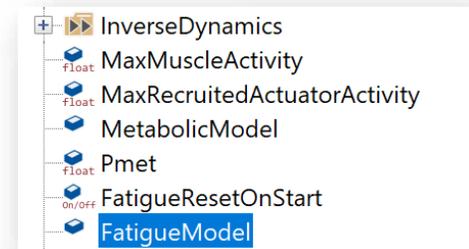
- Better Performance:
 - Faster load times
 - Faster model simulation times
 - Much more robust FDK simulations
- New Advanced Features for Body Modeling
 1. Fatigue/metabolism modeling support
 2. New Inertia Objects based on Geometries
 3. New Volume kinematic measure



2.

```
AnyInertiaSolid BoneInertiaObject = {
  AnySurfSTL surface = {
    FileName = ..BoneDraw.FileName;
    AnyFunTransform3D &scale = ..Scale;
  };
};
```

3.



Feature: Splitting Recruited forces

- Recruited forces are the foundation of AnyBody
- All Recruited forces were modelled as “muscles”

New in AMS 8:

- Distinction between real and artificial muscles

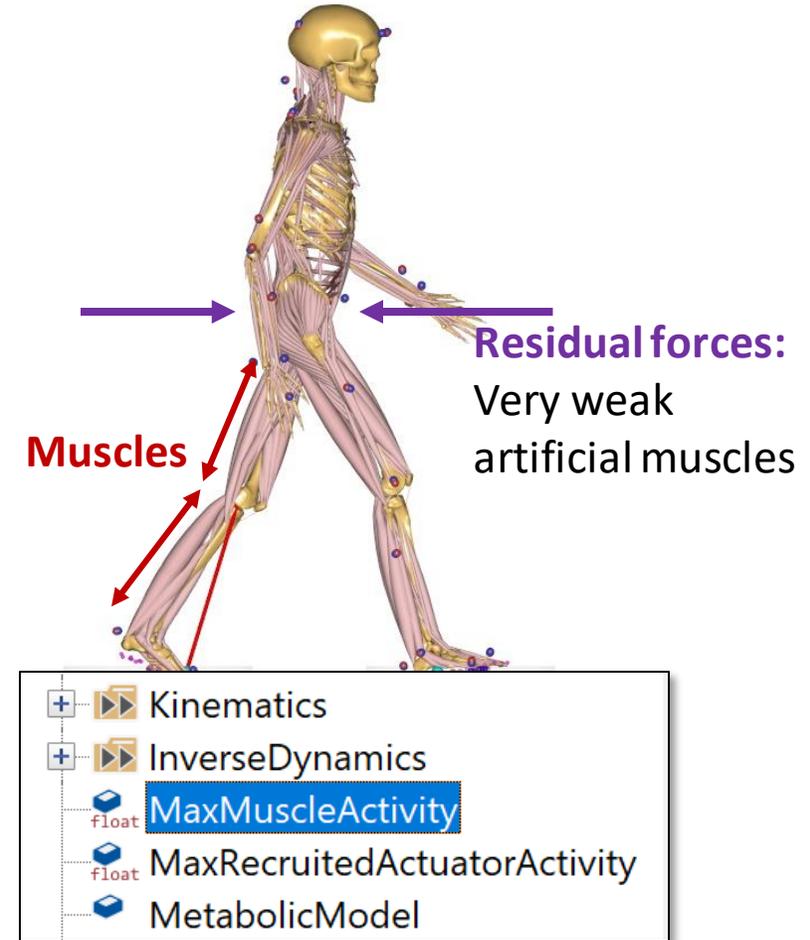
→ AnyRecruitedActuator

- Ground reactions
- Residuals forces
- Other



AnyMuscle

- Muscles
- Physiological actuators



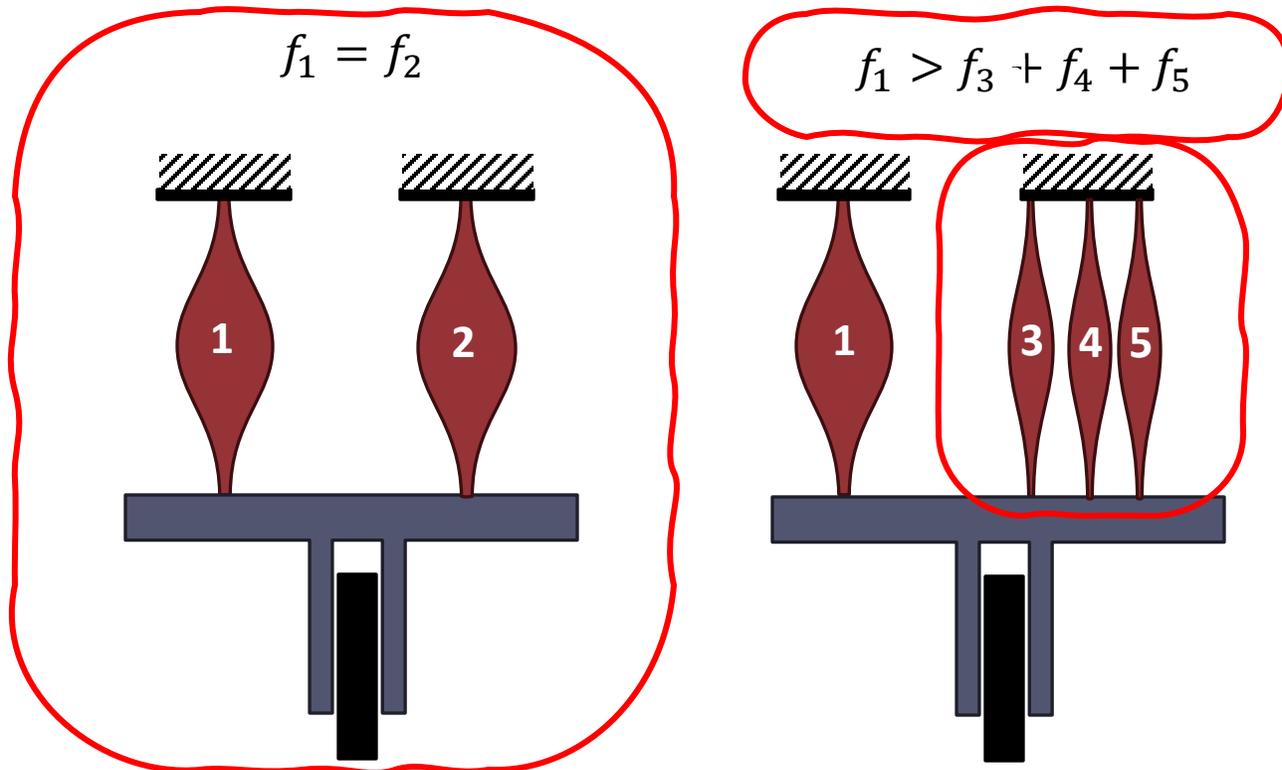
Volume Weighted recruitment

- New recruitment criterion.
- Solves the “muscle discretization” problem.

Polynomial recruitment criterion:

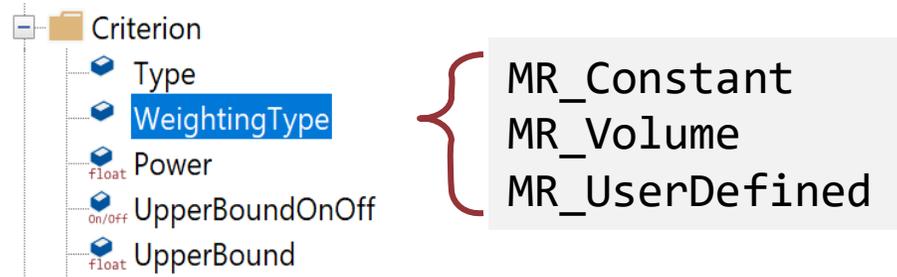
$$J(\mathbf{f}^M) = \sum_{i=1}^n \left(\frac{f_i^M}{N_i} \right)^p$$

Minimize
muscle activation



Volume Weighted recruitment

- Solution -> Volume weighted recruitment
- This is now natively supported by AnyBody



- Still experimental:
 - Not all muscles have a volume in AMMR 3
 - How should Recruited-actuators be weighted

Weighted by Muscle volume

$$J(\mathbf{f}^M) = \sum_{i=1}^n w_i \left(\frac{f_i^M}{N_i} \right)^p$$

(Note: In the original image, w_i is circled in red and an arrow points to it from the text 'Weighted by Muscle volume'.)



Feature: Object pointer improvements

- Many classes now accept object pointers instead of references.

```
AnyFolder& Foot_Reference = Leg.Seg.Foot;
AnyObjectPtr Foot_Pointer = &Leg.Seg.Foot;
```

Explicit references no longer necessary

Example: Center of Mass measure [AnyKinCoM](#)

```
AnyKinCoM CenterOfMass = {
    #if BM_ARM_RIGHT
        AnyFolder &RightArmSeg = ..Right.ShoulderArm.Seg;
    #endif

    #if BM_ARM_LEFT
        AnyFolder &LeftArmSeg = ..Left.ShoulderArm.Seg;
    #endif
}
```

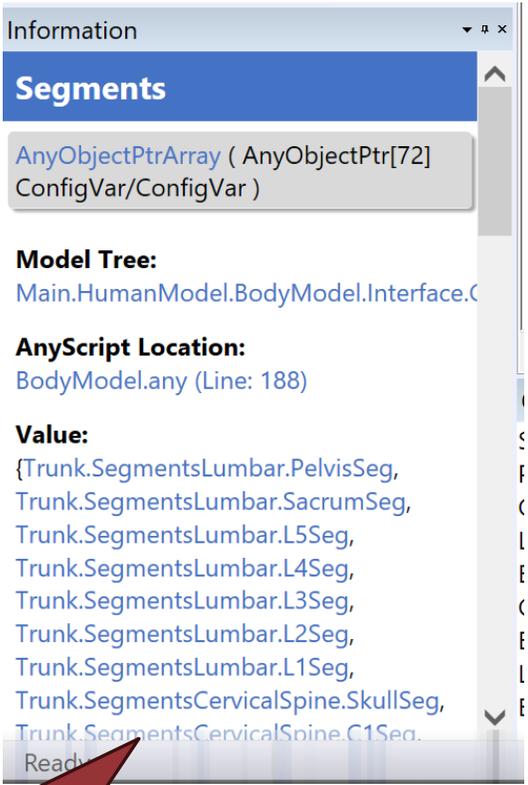
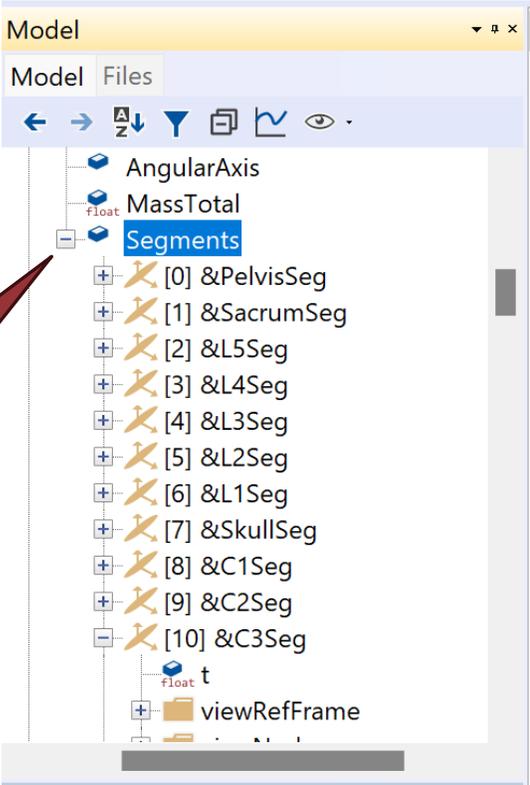
```
AnyKinCoM CenterOfMass = {
    RefFrames = ObjSearchRecursive( &...BodyModel, "*", "AnySeg");
};
```

All objects are found with a search function

Feature: Object pointer improvements

- New functions for pointer arrays
 - ObjGetMember(...)
 - ObjGetParent(...)
 - ObjRefResolve(...)
 - ObjFilterByClass(...)
 - ObjFilterByName(...)
 - ObjFilterByValue(...)
 - ObjSearch(...)
 - ObjSearchRecursive(...)

Model three expands pointer arrays



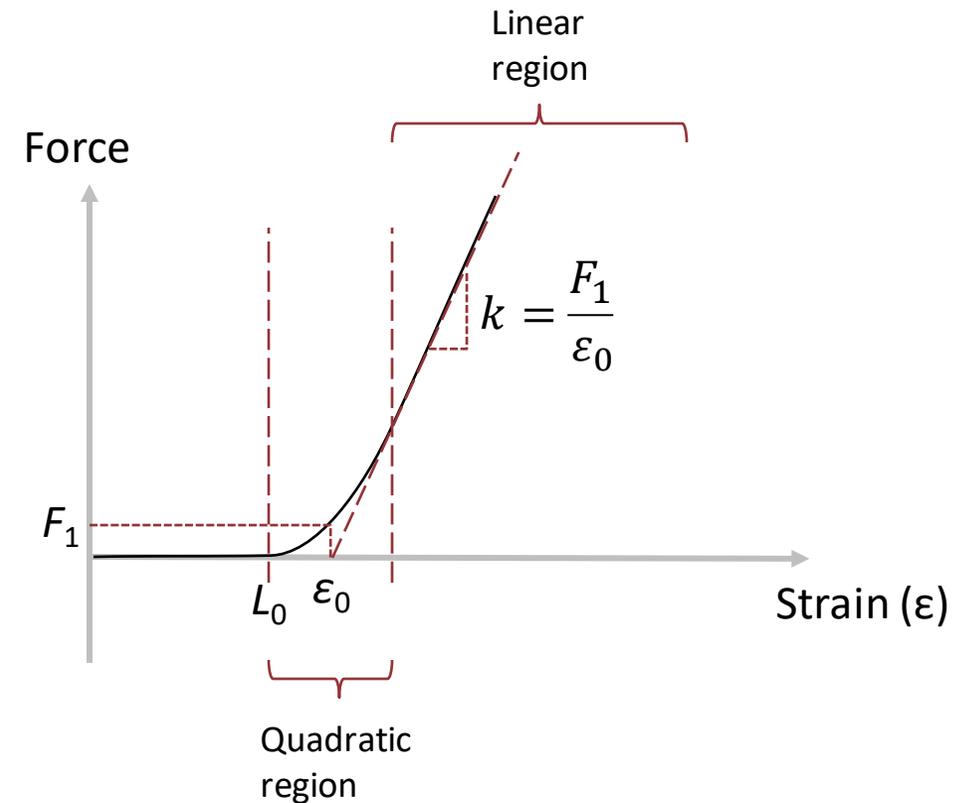
Pointer arrays are links in information window

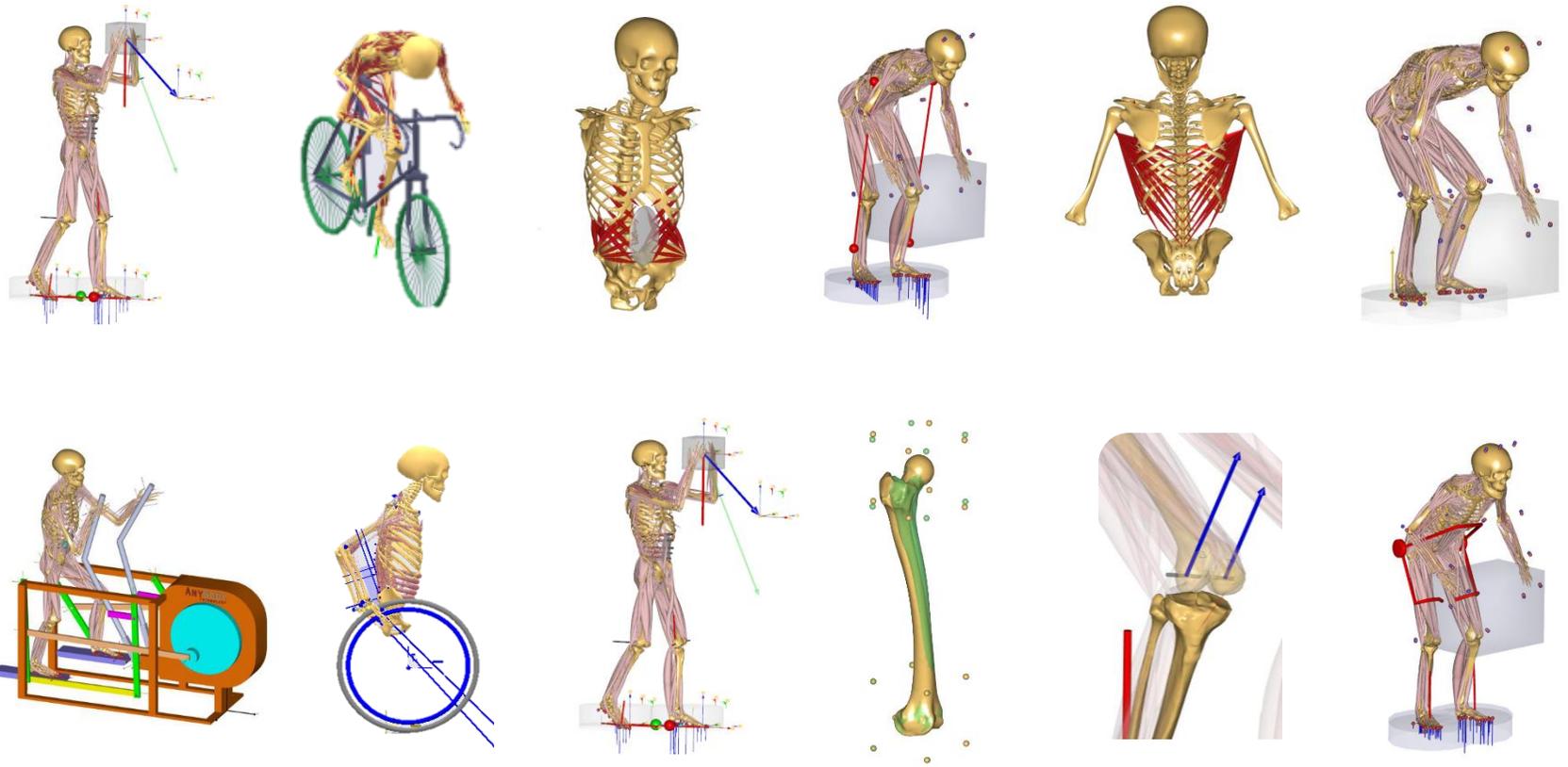
New Ligament Models

- New Ligament model often found in literature

```
AnyLigamentModelQuadLin MyLigament = {
    L0 = 1.30; // Slack length
    eps0 = 0.2; // Strain where F1 is valid
    epsr ??= eps0; // Calibration reference strain initiated to be eps0
    AnyVar F1 = 1000; // Force in the ligament at strain eps0
    k = F1 / eps0;
};
```

- New calibration option for ligaments
 - Allow for calibration at a reference strain ϵ_r (epsr), instead of slack length (L0).



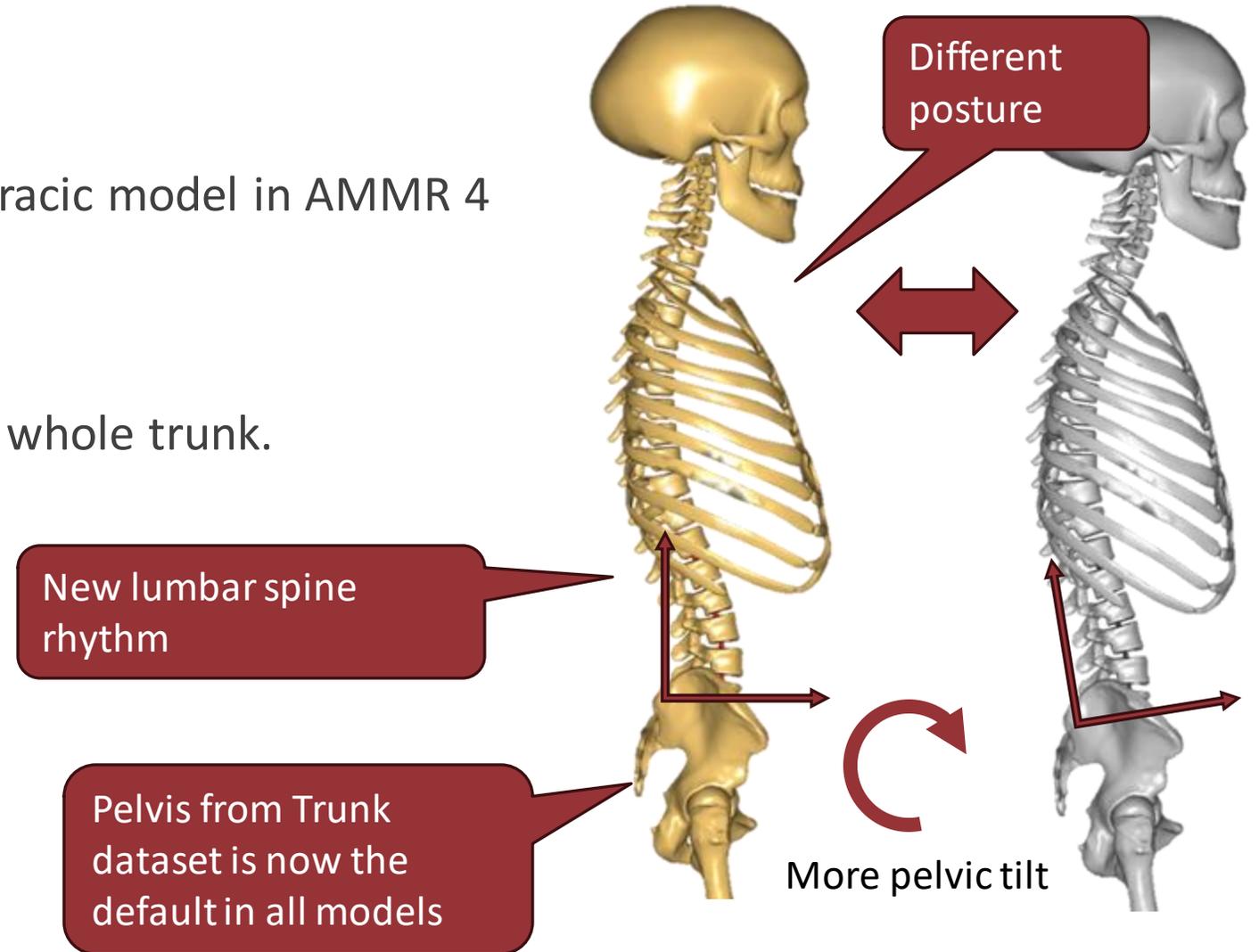


Model repository

✦ Highlights from AMMR 3

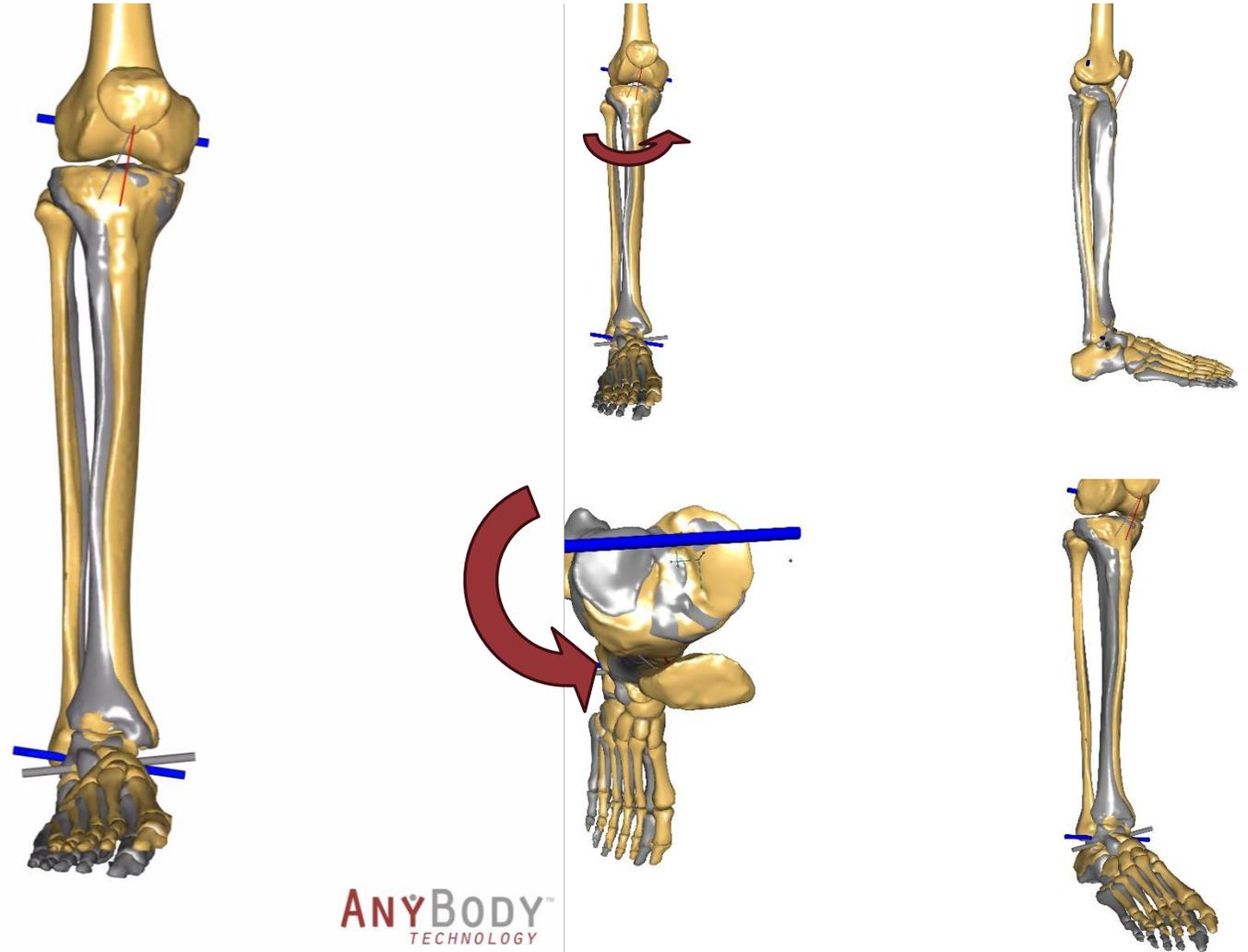
Unified trunk model

- Preparation for the detailed thoracic model in AMMR 4
- Unified/common dataset of the whole trunk.



New updated Leg Model (TLEM 2.2)

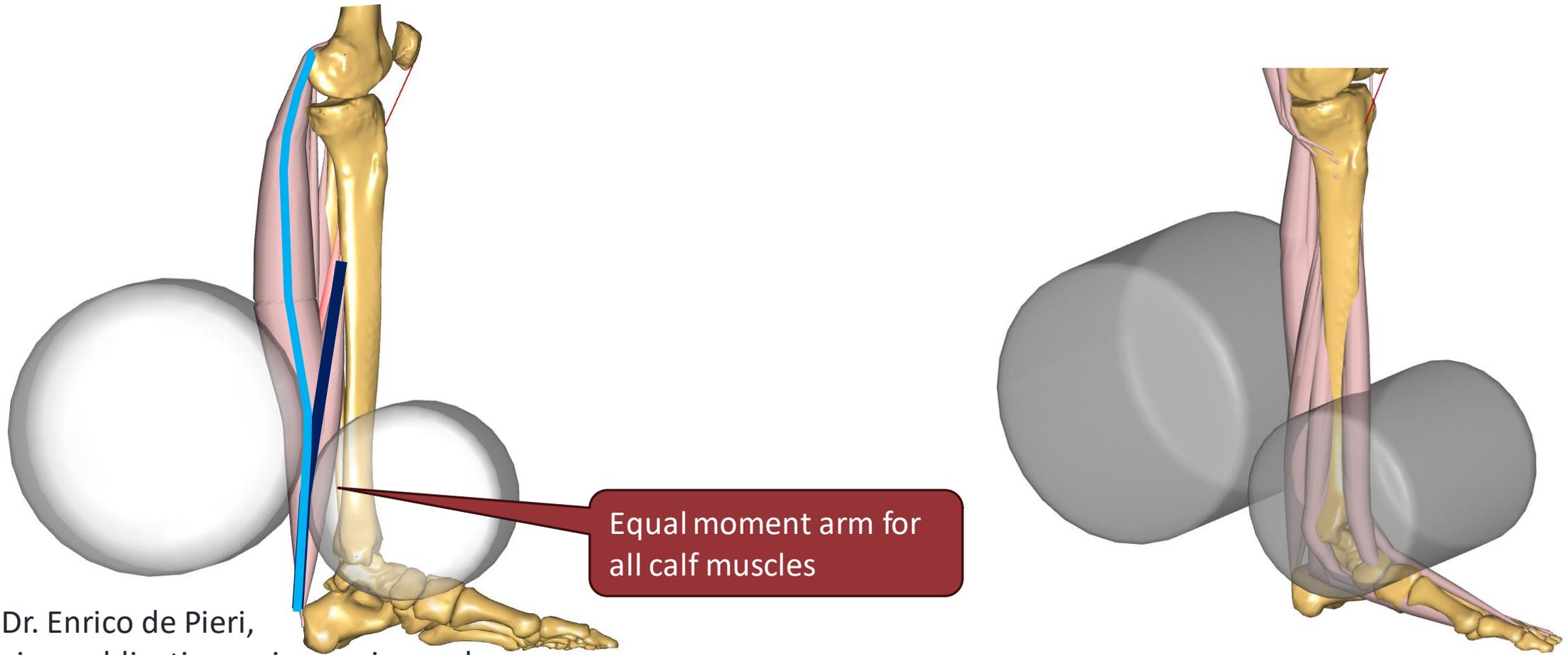
- Compensation for non-neutral scan of original cadaver dataset
- New alignment of the shank
 - Rotation around the tibia long axis
 - New knee/ankle axis in the shank frame.



Credit: Dr. Enrico de Pieri,
- Upcoming publication on improving and
validating the TLEM 2 leg model.

New updated Leg Model (TLEM 2.2)

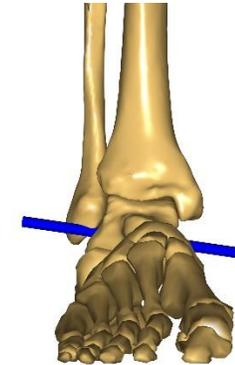
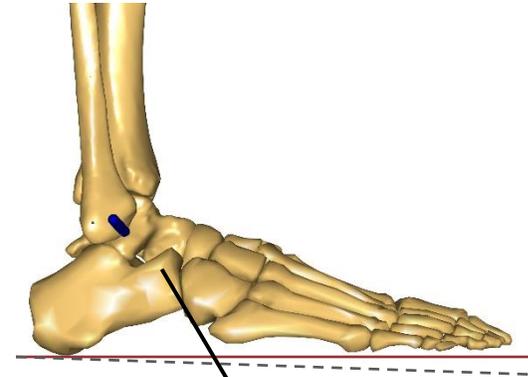
New wrapping for calf muscles



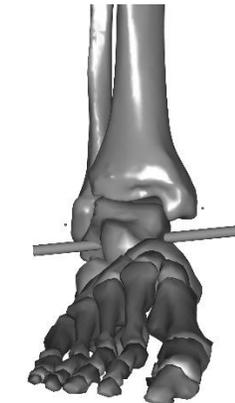
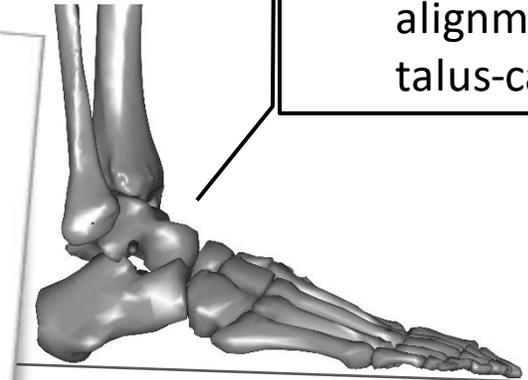
Credit: Dr. Enrico de Pieri,
- Upcoming publication on improving and
validating the TLEM 2 leg model.

New updated Leg TLEM2.2

- Updates to the ankle complex:
 - Updated ankle joint axis based on talus geometry.
- Preparation for new three segment foot model.



Improved alignment of tibia-talus-calcaneus.



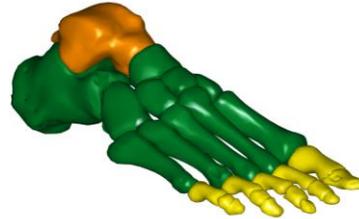
Planned updates for foot model

Rigid foot model (current):



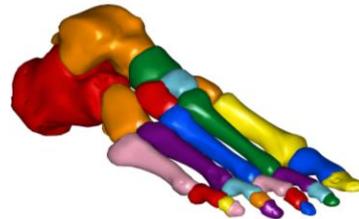
Rigid foot with toe flexion:

- Better fidelity for MoCap



Detailed foot model:

- 26 segments
- Based on Glasgow-Maastricht Foot Model
- For detailed foot research



Work in progress



Rigid foot with toe flexion

New Model Documentation

<https://anyscript.org/ammr>

🌟 New highlights

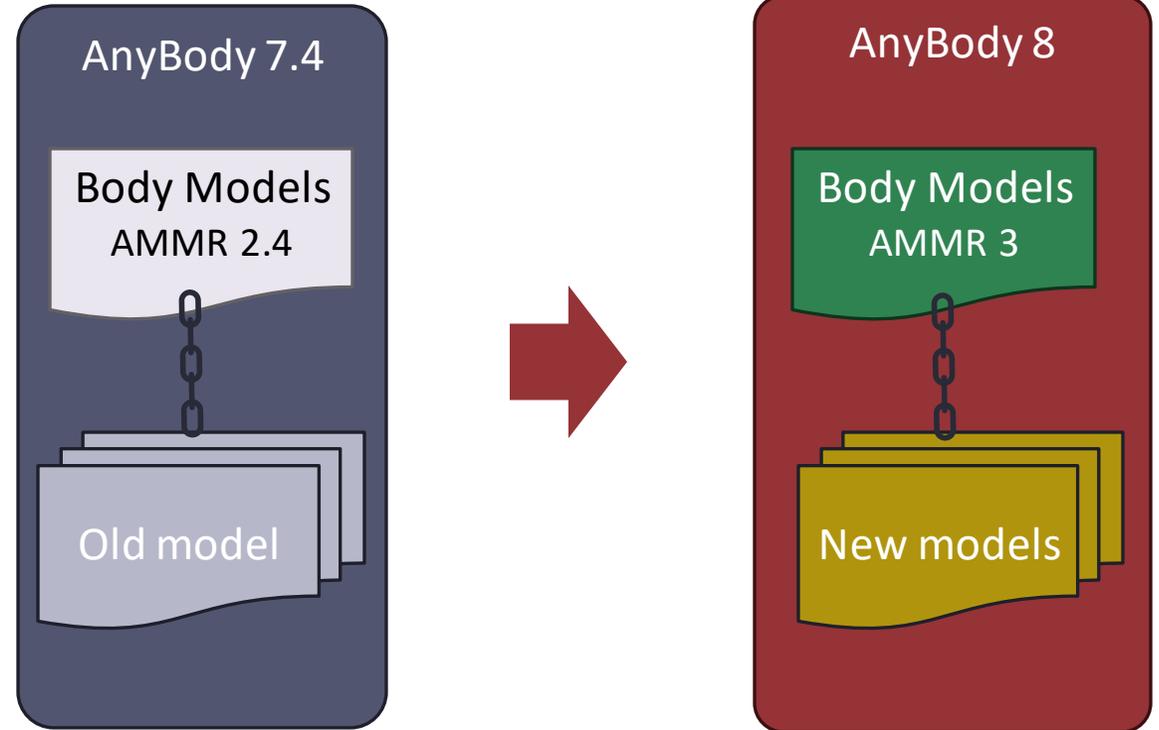
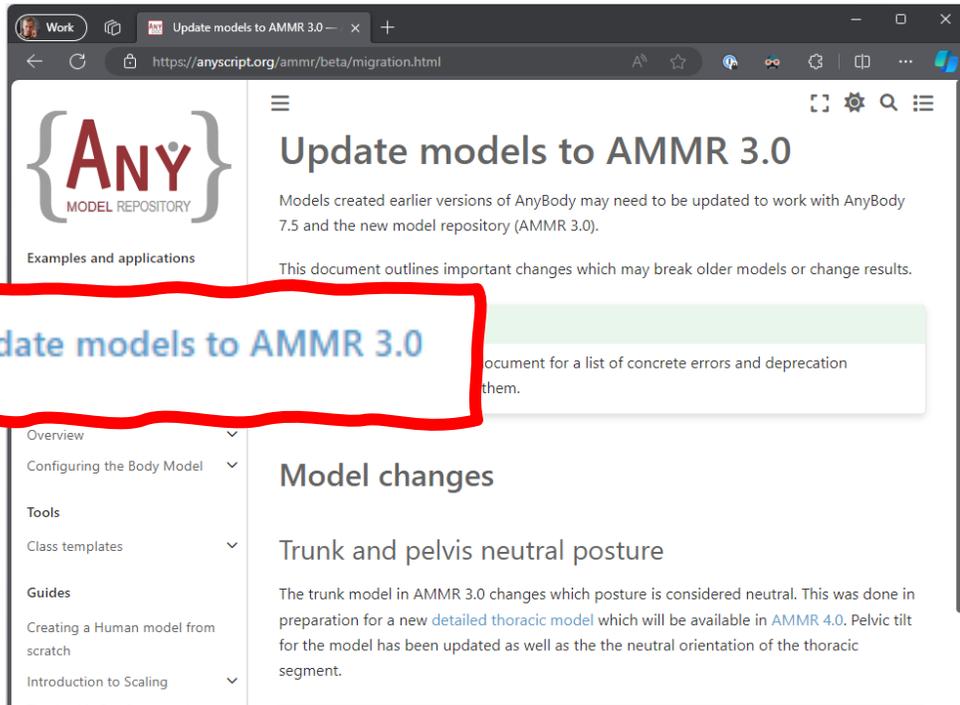
Tools
Class templates

About
Changelog

The screenshot shows the AMMR website interface. The sidebar on the left has a menu with the following items: 'Tools' (highlighted with a red box), 'Class templates' (highlighted with a red box), 'Guides', 'About' (highlighted with a red box), and 'Changelog' (highlighted with a red box). The main content area includes a header with the title 'The AnyBody Managed Model Repository' and a 'New in AMMR 3.0.0-beta' button. Below the header, there are sections for 'Open body models', 'Configurable Human model', 'Lots of Application examples', and 'Community effort'. At the bottom, there are three cards: 'Body Models', 'Example gallery', and 'Model Configuration'.

Migrating models to AMMR 3

- Detailed guide on porting old models



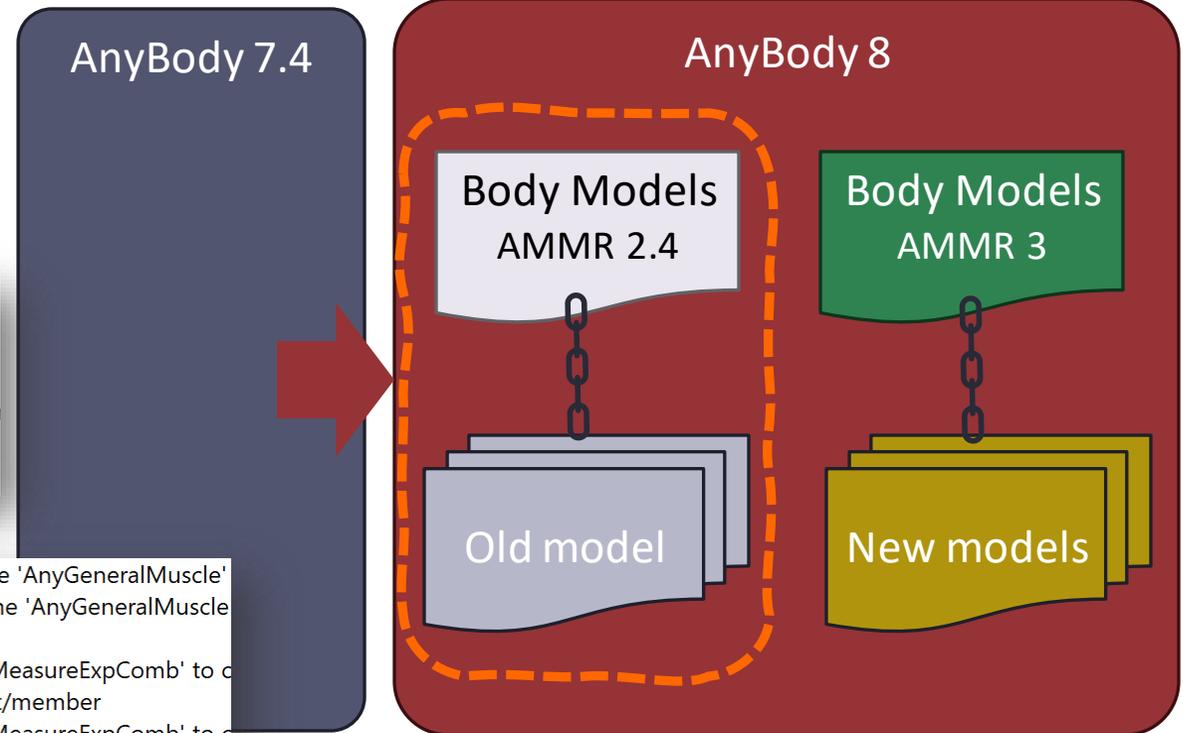
Porting old models AnyBody 8...

Old Models, and old AMMR:

 Expect deprecation warning...

```
AMMR version detected : 2.4.4
[System.Compatibility.AnyBody75_AMMR24_CompatibilityOnOff] set to :On'
WARNING(SYS7) : AnyBody75\_AMMR24\_CompatibilityOnOff : Compatibility mode auto-detected :
- AnyMuscle::MuscleModel is renamed to '_MuscleModel' to avoid conflict with AMMR definitions.
It is recommended to update to a newer AMMR, or set this compatibility-mode to 'Off' and fix conflicts in
Parsing...
Constructing model tree...
```

```
NOTICE(SYS3) : DiagnosticMuscle2.any\(13\) : PosMuscle : AnyGeneralMuscle : Deprecated class : The 'AnyGeneralMuscle'
NOTICE(SYS3) : DiagnosticMuscle2.any\(21\) : NegMuscle : AnyGeneralMuscle : Deprecated class : The 'AnyGeneralMuscle'
WARNING(SYS4) : Jnt.any\(226\) : Measure1.NormedMeasureOnOff : Deprecated object/member
'NormedMeasureOnOff', 'Base', and 'Exponent' are deprecated. It is recommended to use class 'AnyKinMeasureExpComb' to c
WARNING(SYS4) : Jnt.any\(389\) : ScapulaTSThoraxMeasure.NormedMeasureOnOff : Deprecated object/member
'NormedMeasureOnOff', 'Base', and 'Exponent' are deprecated. It is recommended to use class 'AnyKinMeasureExpComb' to c
WARNING(SYS4) : Jnt.any\(226\) : Measure1.NormedMeasureOnOff : Deprecated object/member
'NormedMeasureOnOff', 'Base', and 'Exponent' are deprecated. It is recommended to use class 'AnyKinMeasureExpComb' to c
WARNING(SYS4) : Jnt.any\(389\) : ScapulaTSThoraxMeasure.NormedMeasureOnOff : Deprecated object/member
'NormedMeasureOnOff', 'Base', and 'Exponent' are deprecated. It is recommended to use class 'AnyKinMeasureExpComb' to c
Evaluating constants...
Configuring model...
```



Porting old models AnyBody 8...

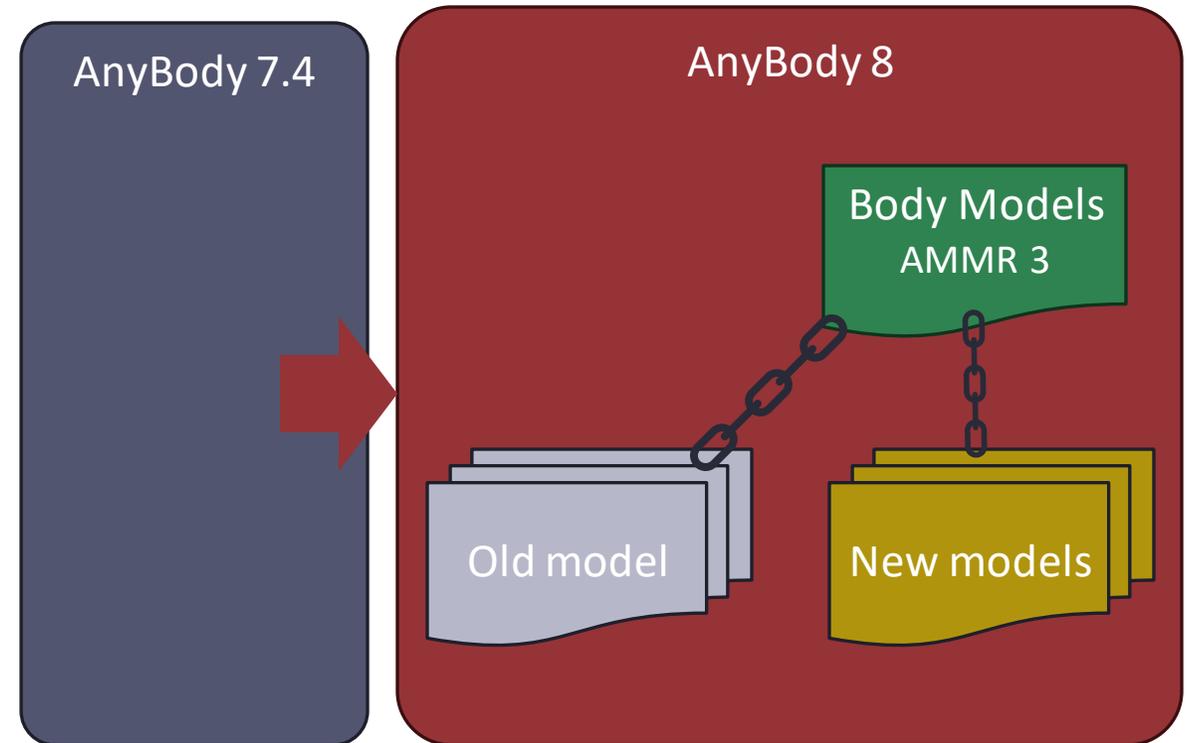
Old Models, and old AMMR:

📌 Expect deprecation warning...

Old Models + new AMMR (3.0)

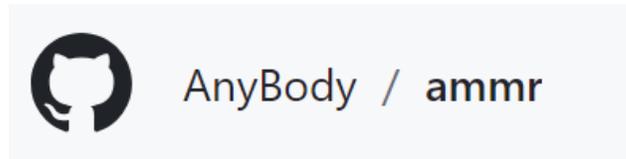
✓ Simple models are OK

✗ Complex models **needs changes**

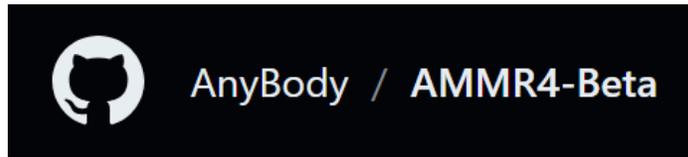


Follow model development on GitHub

- Contribute any changes and fixes:

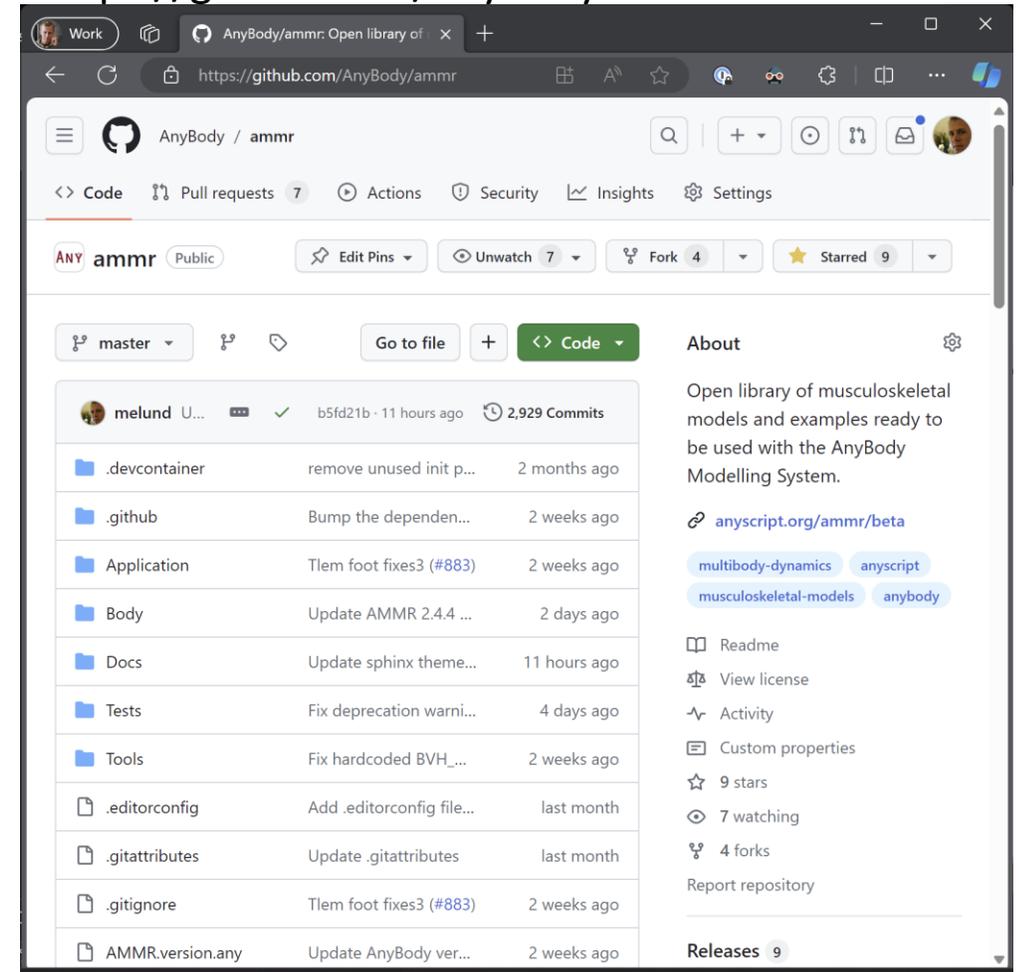


- Next version of AMMR (v.4) is available now:



- ❖ New Thoracic model
- ❖ New abdominal pressure model
- ❖ Foot models are coming

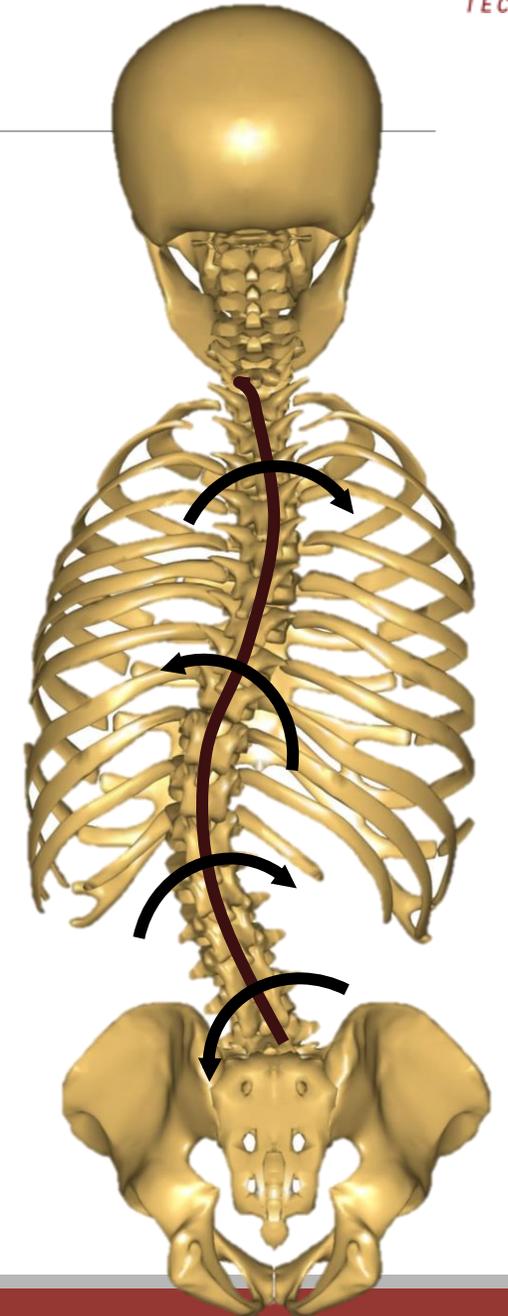
<https://github.com/anybody>



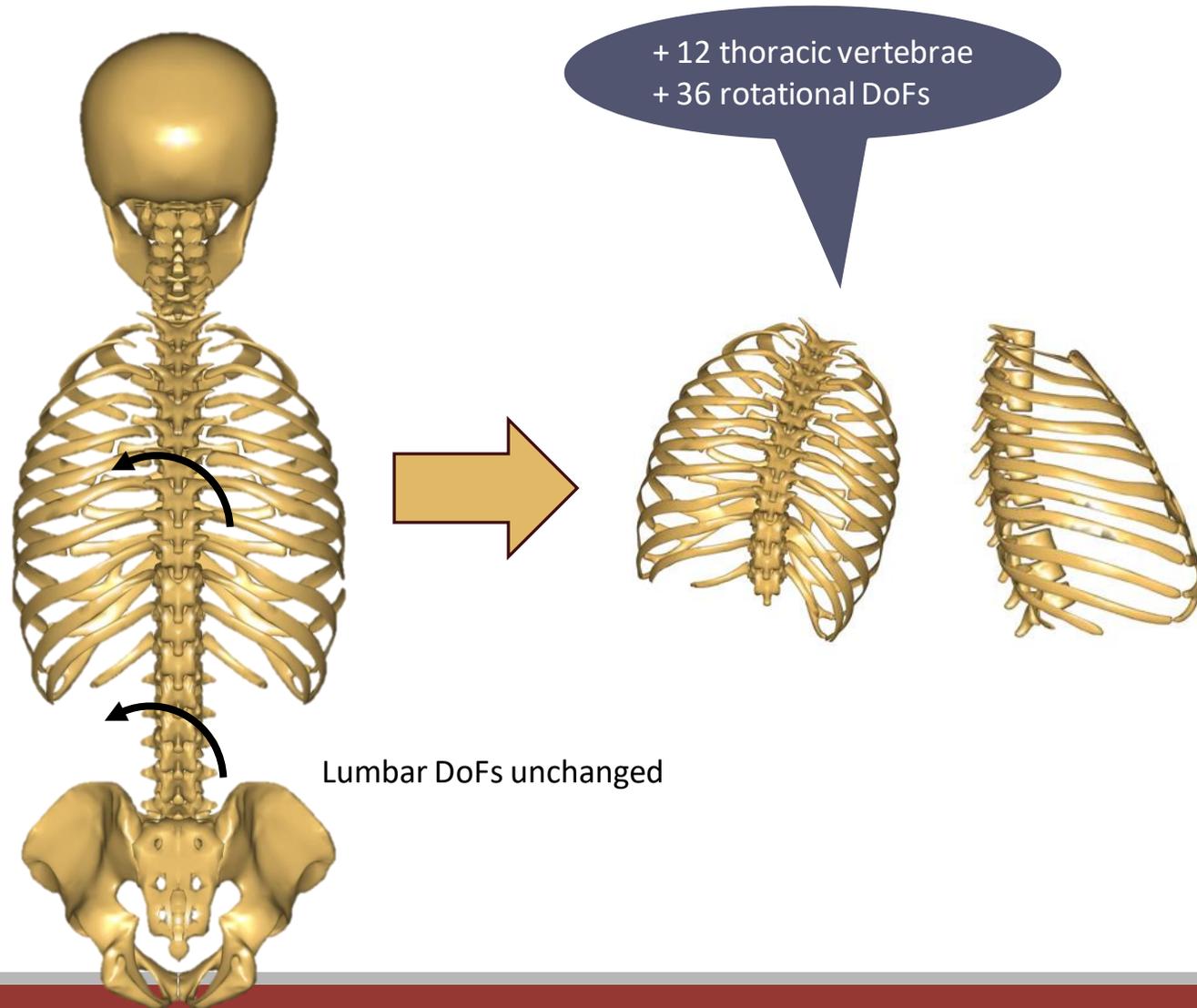
New Thoracic Model

- Model in development and validation
- Available on GitHub:
<https://github.com/anybody/ammr4-beta>
- Multiple papers underway:
 1. **Shayestehpour, H.**, Rasmussen, J., Galibarov, P., Wong, C.: An articulated spine and ribcage kinematic model for simulation of scoliosis deformities. *Multibody Syst. Dyn.* 53, 115–134 (2021).
<https://doi.org/10.1007/s11044-021-09787-9> (Published)
 2. A generic detailed multibody thoracic spine and ribcage model. **Hamed Shayestehpour**, Søren Tørholm, Michael Damsgaard, Morten Lund, Christian Wong, John Rasmussen, *Multibody Syst. Dyn.*
 3. A generic detailed multibody abdominal and diaphragm model. **Hamed Shayestehpour**, Søren Tørholm, Michael Damsgaard, Morten Lund, Christian Wong, John Rasmussen, *Multibody Syst. Dyn.*
 4. Kinetic investigation of a thoracolumbar spine model including the ribcage. **Hamed Shayestehpour**, Mohammad Amin Shayestehpour, Christian Wong, John Rasmussen, *Journal of Biomechanics*.

2,3,4: Not published yet.



Spine DoFs

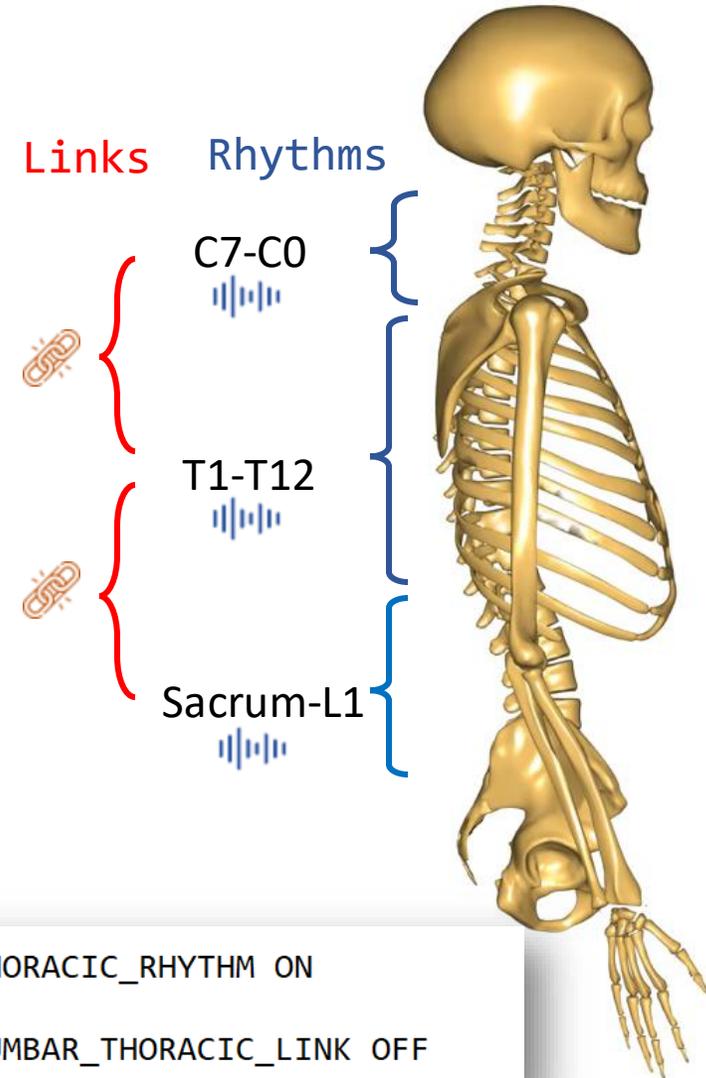
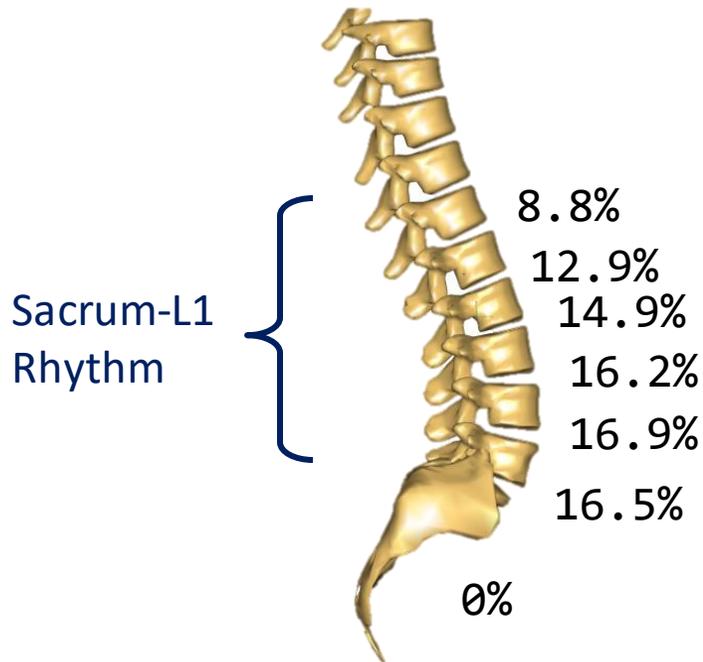


🌟 Key highlights:

1. Detailed ribcage simulations since ribs and sternum are separate
2. Determinate ribcage kinematics → no need for extra input DoFs
3. Freely specify entire spinal posture → ribs and sternum will follow.

Spine Rhythms

- Full Thoracic model has more Dofs
 - + 228 extra total DoFs
- Rhythms make models easy to use.

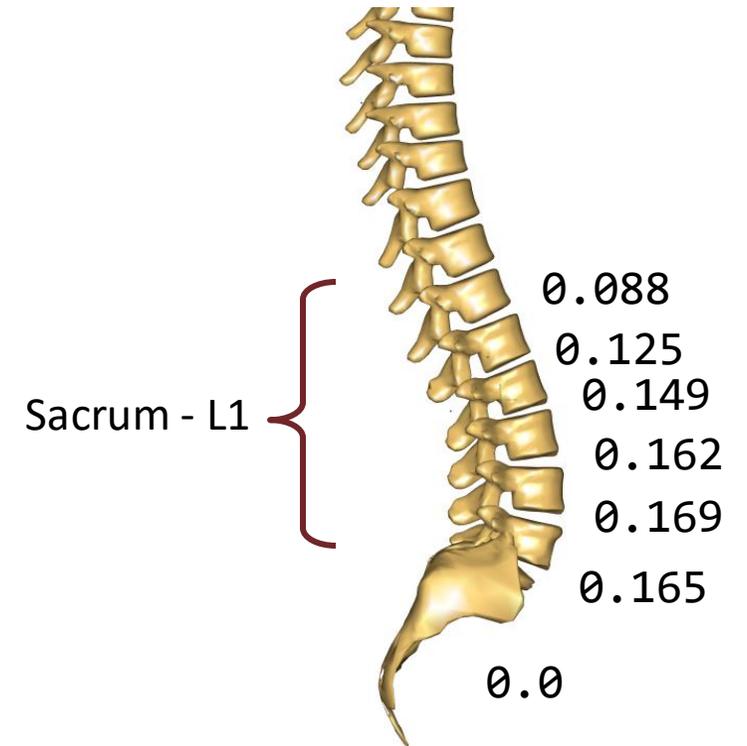


```
#define BM_TRUNK_THORACIC_RHYTHM ON
#define BM_TRUNK_LUMBAR_THORACIC_LINK OFF
```

New `#class_template` tool



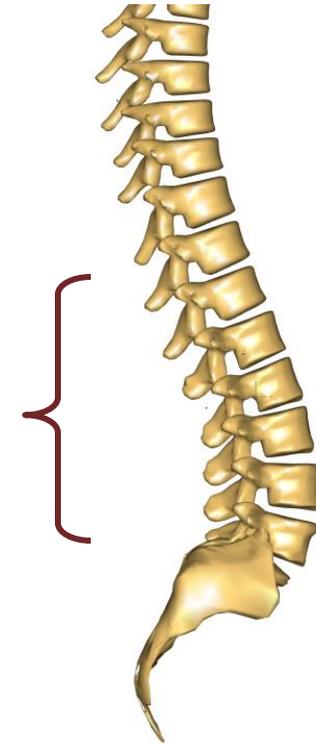
```
RhythmDriverLinear SpineRhythmDrvFlexion() = {
    RhythmCoefficients = {};
    Measures.Input = {
        AnyJoint &u1 = ...SacrumPelvis;
        AnyJoint &u2 = ...L5Sacrum;
        AnyJoint &u3 = ...L4L5;
        AnyJoint &u4 = ...L3L4;
        AnyJoint &u5 = ...L2L3;
        AnyJoint &u6 = ...L1L2;
        AnyJoint &u7 = ...T12L1;
        MeasureOrganizer = {2, 5, 8, 11, 14, 17, 20};
    };
};
```



```

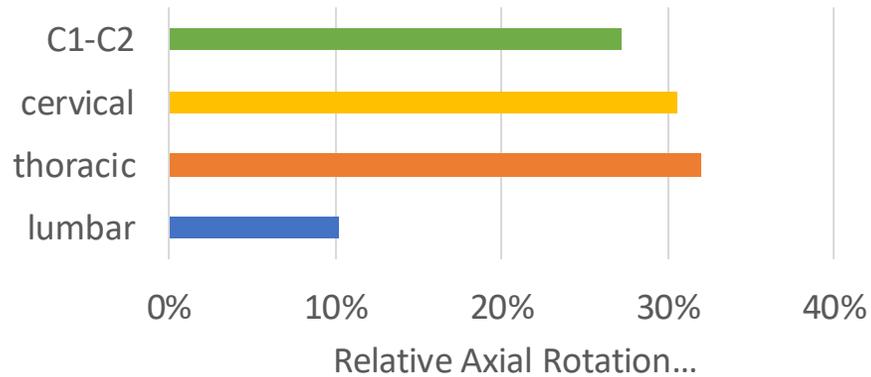
RhythmDriverLinear SpineRhythmDrvFlexion() = {
  RhythmCoefficients = { 0.0, 0.165, 0.169, 0.162, 0.149, 0.125, 0.088};
  Measures.Input = {
    AnyJoint &u1 = ...SacrumPelvis;
    AnyJoint &u2 = ...L5Sacrum;
    AnyJoint &u3 = ...L4L5;
    AnyJoint &u4 = ...L3L4;
    AnyJoint &u5 = ...L2L3;
    AnyJoint &u6 = ...L1L2;
    AnyJoint &u7 = ...T12L1;
    MeasureOrganizer = {2, 5, 8, 11, 14, 17, 20};
  };
};

```



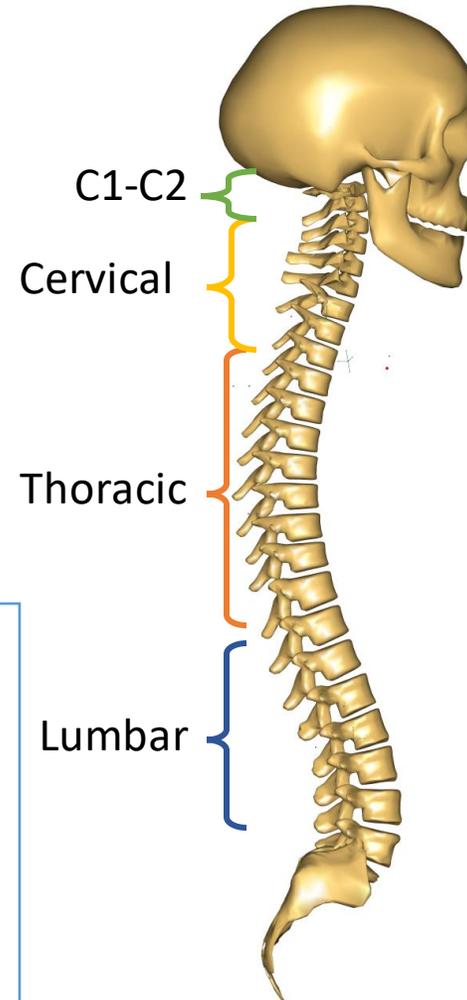
Rhythm coefficients – Axial rotation

Links

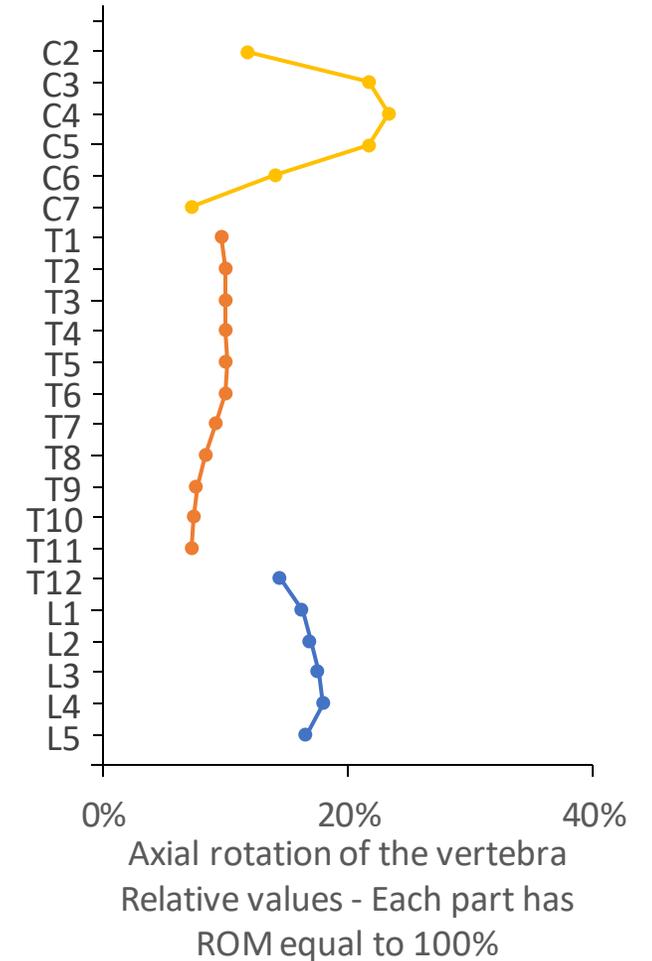


```

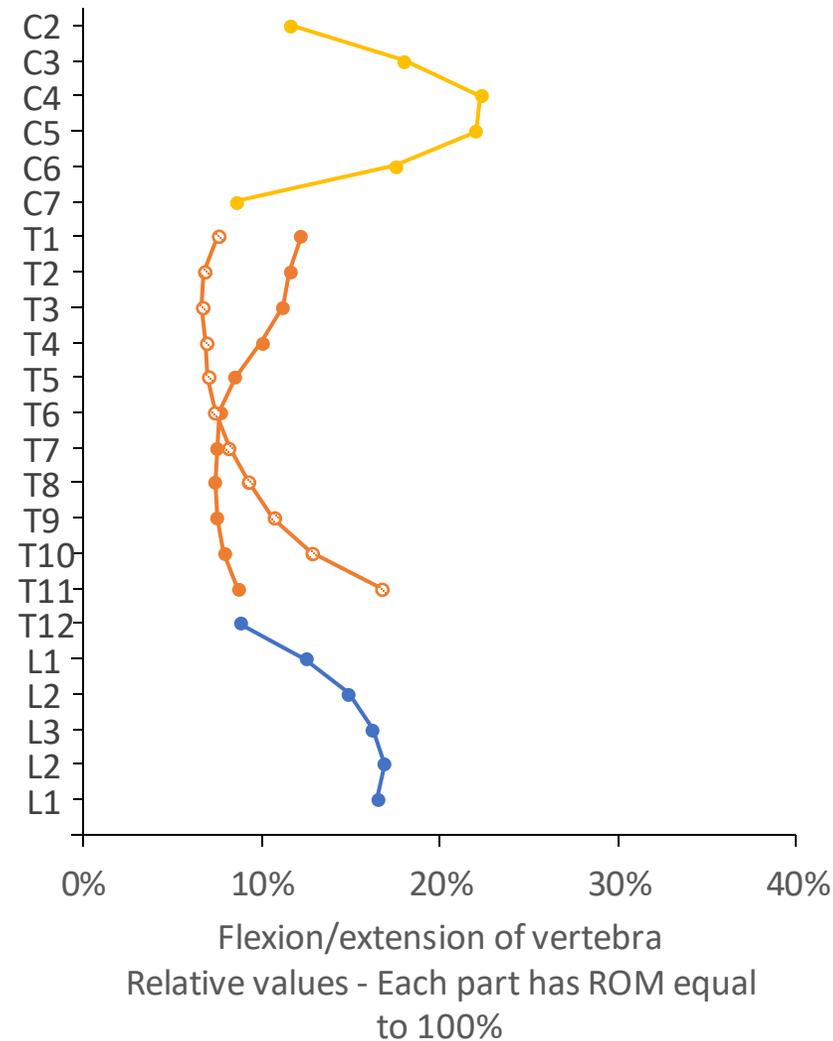
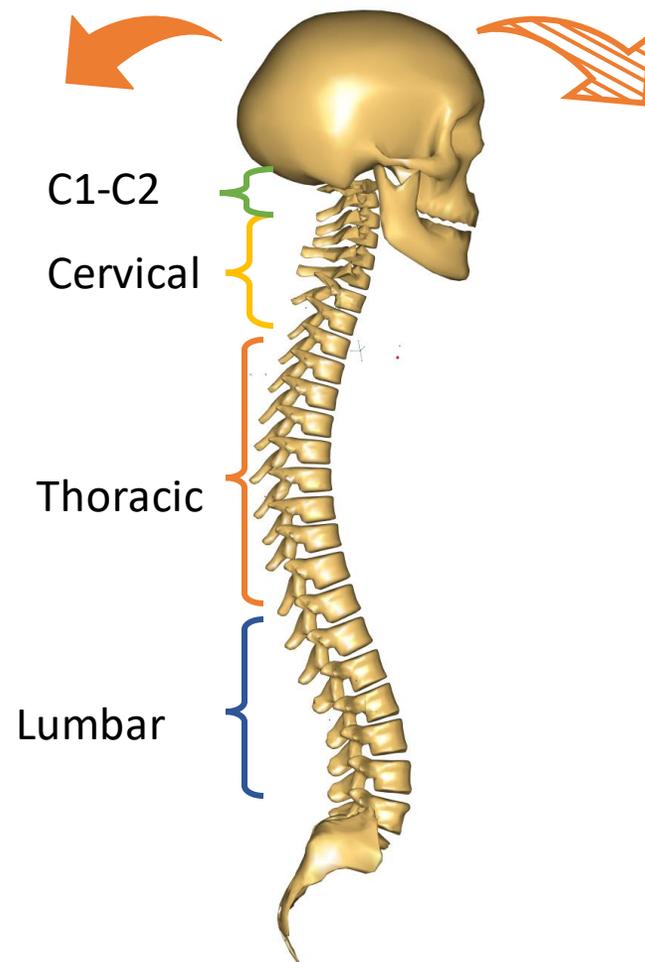
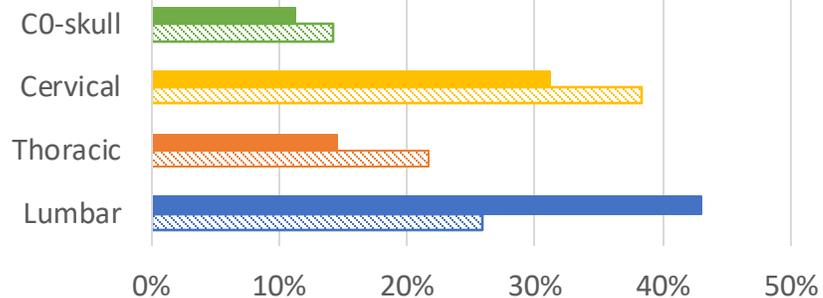
RhythmDriverLinear SpineRhythmDrvFlexion() = {
  RhythmCoefficients = {0, 0.165, 0.169, 0.162, 0.149, 0.125, 0.088};
  Measures.Input = {
    AnyJoint &u1 = ...SacrumPelvis;
    AnyJoint &u2 = ...L5Sacrum;
    AnyJoint &u3 = ...L4L5;
    AnyJoint &u4 = ...L3L4;
    AnyJoint &u5 = ...L2L3;
    AnyJoint &u6 = ...L1L2;
    AnyJoint &u7 = ...T12L1;
    MeasureOrganizer = {2, 5, 8, 11, 14, 17, 20};
  };
};
  
```



Rhythms

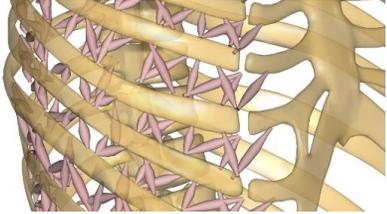


Rhythm coefficients - Flexion/extension

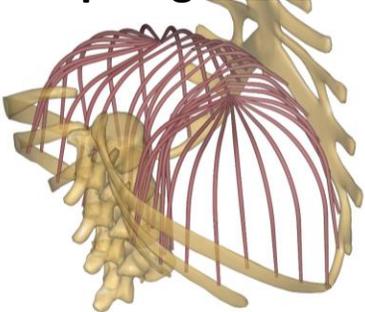


Detailed muscle and ligament configuration

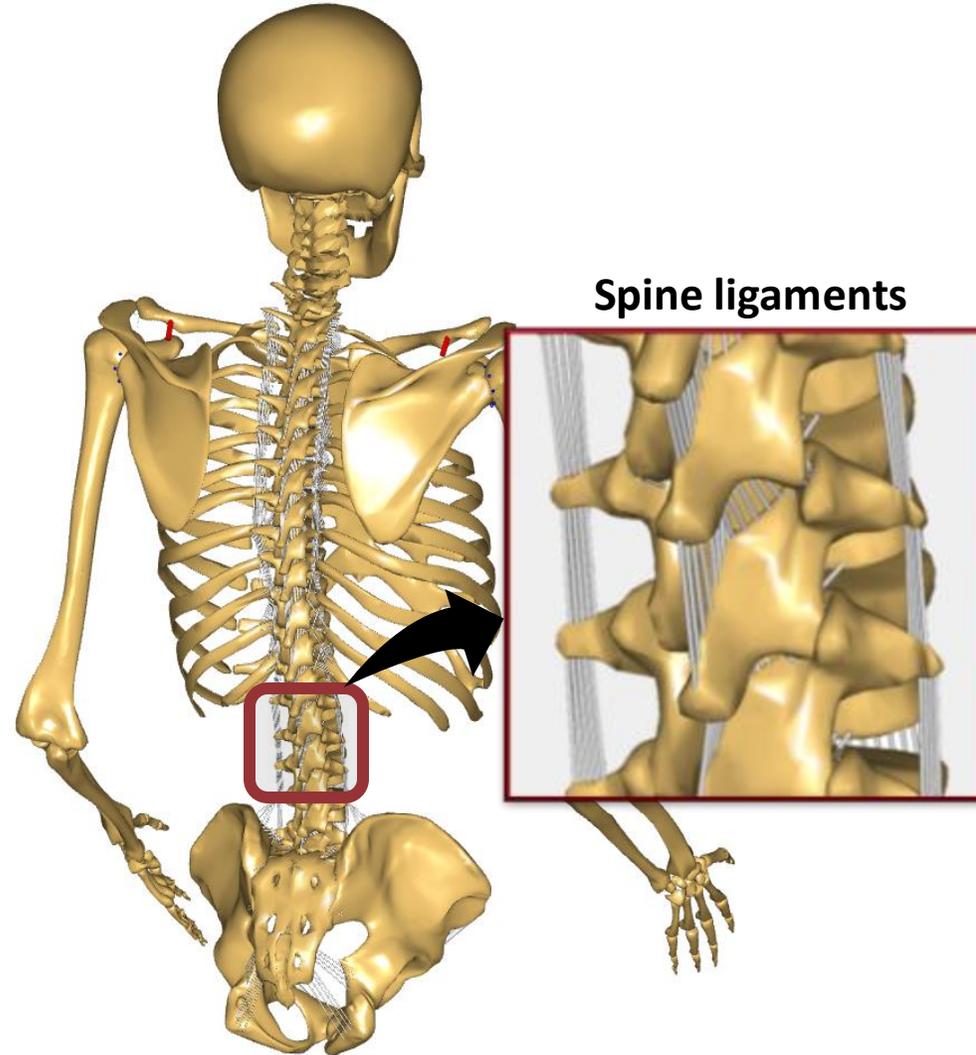
Intercostals muscles



Diaphragm muscles

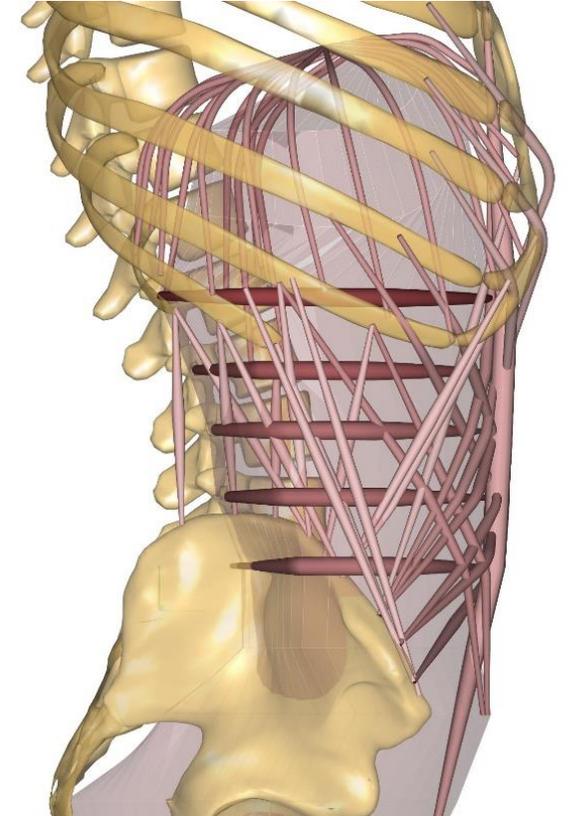


Obliquus muscles



Spine ligaments

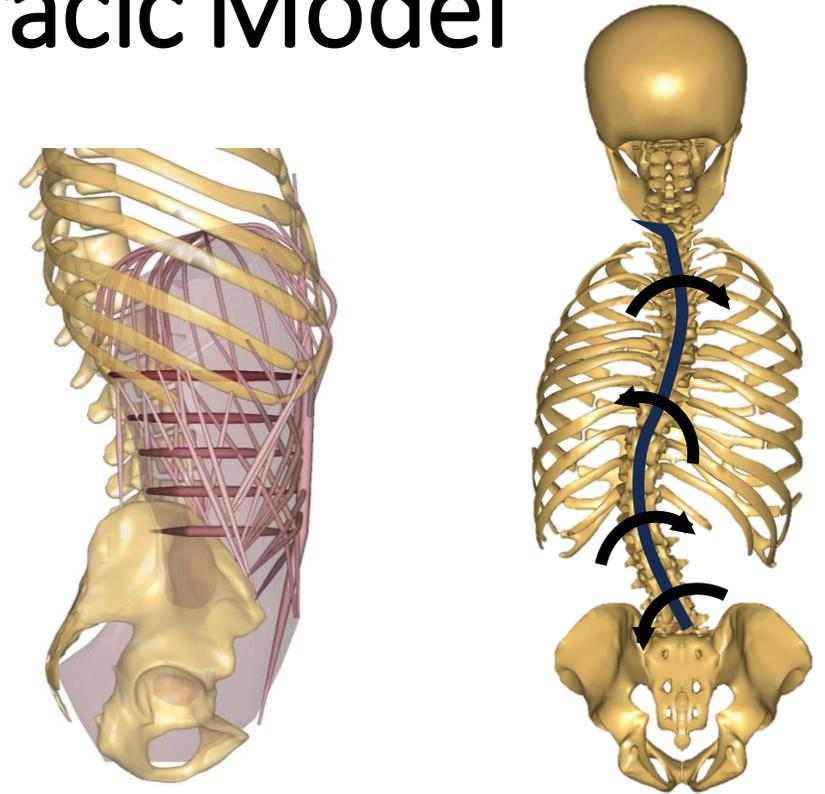
Abdominal pressure model



Upcoming Webcast: New Thoracic Model

Detailed thoracic model abdominal model

- Date: Announced soon.
- Presenters:
 - Søren Tørholm (cofounder of AnyBody)
 - Hamed Shayestehpour (Engineer at AnyBody)



Try it now: <https://github.com/anybody/AMMR4-Beta>



Questions

 **Meet us**

- Send email to sales@anybodytech.com

 **Trial version**

- Send email to sales@anybodytech.com

 **Presentation questions**

- Send email to ki@anybodytech.com

