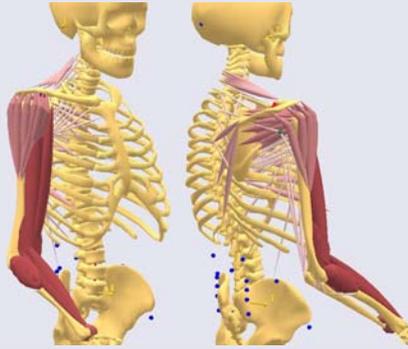


# Validation of the AnyBody version of the Dutch Shoulder Model

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The AnyBody Research Group  
Department of Mechanical Engineering  
Aalborg University



The web cast will start in a few minutes....

Why not spend the time checking these points:

Does your screen fit the presentation?

Try this:

The "Sharing" menu (upper right corner)->View->Autofit

Is your system set up to receive the broadcasted sound?

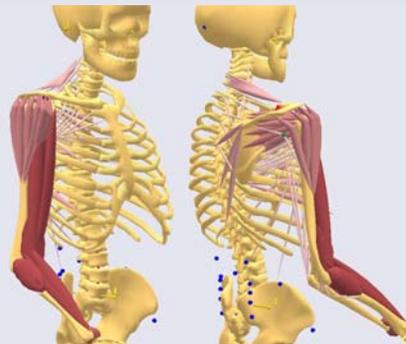
Please follow these instructions to set up the audio:  
[www.anybodytech.com](http://www.anybodytech.com) -> Webcasts (bottom of the page)

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# The shoulder model

- Based on data collected by the Dutch Shoulder Group.
- 118 muscles on each side.
- Wrapping of muscles by contact mechanics.
- Contact criterion in the GH joint.
- Part of the public domain model repository.



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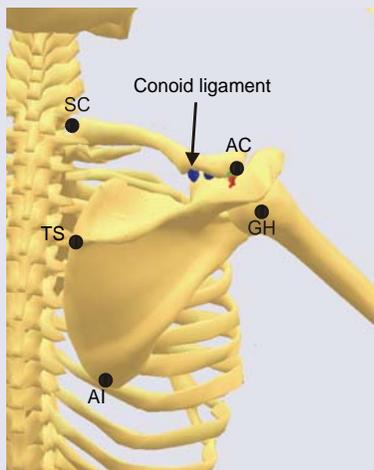
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## The “entire” body model

- More than 500 muscles.
- A few parts missing:
  - Hands
  - Feet
  - Thoracic spine
  - Cervical spine

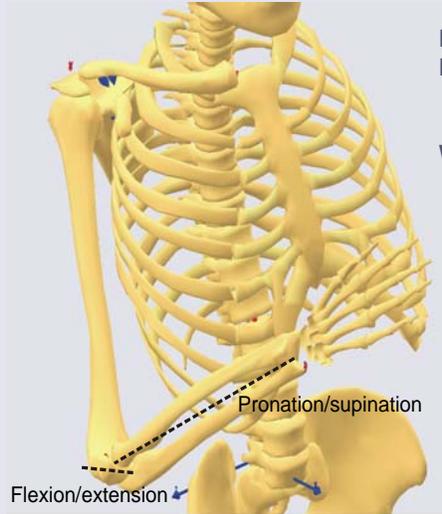


## Shoulder Kinematics



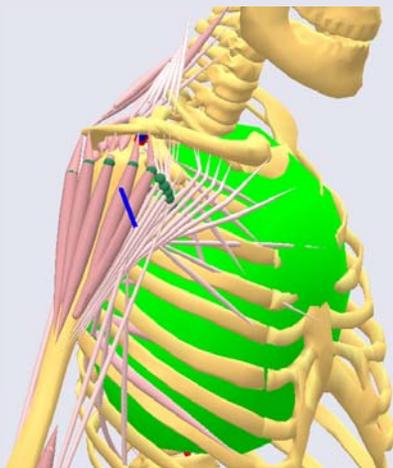
AC	Spherical joint
GH	Spherical joint
SC	Spherical joint
TS	Scapula thoracic gliding plane, ellipsoid
AI	Scapula thoracic gliding plane, ellipsoid

## Arm Kinematics



**FE** Flexion/extension, revolute joint  
**PS** Pronation/supination, combination of joints with one DOF  
**Wrist** Universal joint

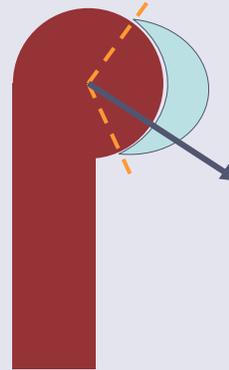
## Muscle wrapping



- Most muscles wrap on analytical surfaces.
- Many muscles wrapping over several surfaces.
- Contact is engaged and released depending on posture.

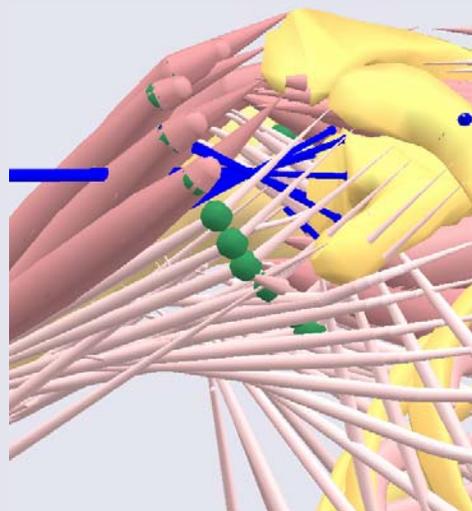
## Gleno-humeral joint stability

- It is a common assumption that the GH joint is not unconditionally stable.
- Muscle recruitment must therefore honor the condition that the reaction force is directed into the glenoid fossa.



## Stability in AnyBody

- Contact elements.
- They can only carry pressure.
- Directed from the edge of the glenoid to the center of the joint.
- Linear combinations can only generate resulting forces inside the glenoid.



# Validation against joint forces

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Journal of Biomechanics ■ (■■■■) ■■■-■■■

JOURNAL  
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BIOMECHANICS

www.elsevier.com/locate/jbiomech  
www.JBiomech.com

## In vivo glenohumeral contact forces—Measurements in the first patient 7 months postoperatively

G. Bergmann<sup>a,\*-1</sup>, F. Graichen<sup>a</sup>, A. Bender<sup>a</sup>, M. Kääh<sup>b</sup>, A. Rohlmann<sup>a</sup>, P. Westerhoff<sup>a</sup>

<sup>a</sup>Department of Orthopaedics, Charité—Universitätsmedizin Berlin, Biomechanics Laboratory, Campus Benjamin Franklin,  
Hindenburgdamm 30, D-12203 Berlin, Germany

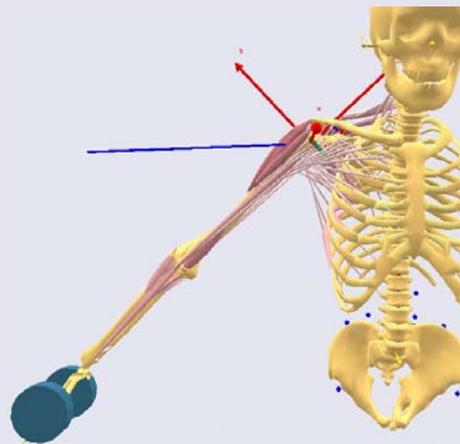
<sup>b</sup>Charité—Universitätsmedizin Berlin, Campus Mitte, Centrum für Muskuloskeletale Chirurgie, Klinik für Orthopädie und Klinik für Unfall- und  
Wiederherstellungschirurgie, Schumannstr. 20-21, D-10117 Berlin, Germany

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## Demo: Abduction with dumbbell



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## Two recruitment criteria:

Minimum fatigue

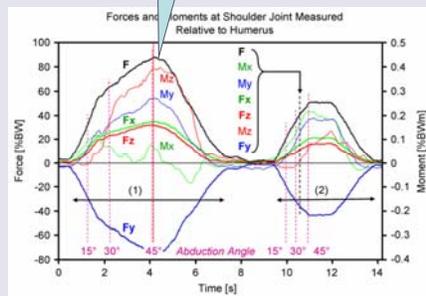
$$\min \max_i \left( \frac{f_i^{(M)}}{N_i} \right)$$

or

$$\min \sum \left( \frac{f_i^{(M)}}{N_i} \right)^2$$

## Results - abduction

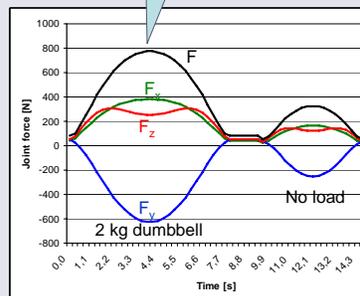
880 N



Bergmann et al

774 N

QP criterion



(With min/max criterion: 1118 N)

## Discussion

- Force profiles indicate that the basic mechanics of the model mimic the real shoulder.
- Accuracy:
  - QP criterion: 12% below Bergmann.
  - Minimum fatigue criterion: 27% above Bergmann.
- Anthropometrical data not adjusted.
  - Segment lengths
  - Segment masses
- Posture uncertainties:
  - Humerus rotation.
  - Scapular-thoracic posture

## Further information

- Modeling discussions and support:  
[tech.groups.yahoo.com/group/anyscript](http://tech.groups.yahoo.com/group/anyscript)
- Papers, references and models:  
[www.anybody.aau.dk](http://www.anybody.aau.dk)
- Software downloads, documentation, newsletter:  
[www.anybodytech.com](http://www.anybodytech.com)

