The webcast will start in a few minutes....



The new AnyBody Modeling System & Musculoskeletal Model Repository

TOUR AND OVERVIEW OF THE NEW 7.2 VERSION



Outline

- General introduction to the modeling system
- New features in the Modeling System
- New Model Repository (AMMR 2.2)
- New help resources and documentation
- Questions and answers



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Control Panel

The Control Panel appears on the right side of your screen.

Submit questions and comments via the Questions panel.

Questions will be addressed at the end of the presentation. If your question is not addressed we will do so by email.





Musculoskeletal Simulation









Load Cases for Finite Element Analysis

Surgical Planning and Outcome Evaluation





AnyBody Modeling System





AnyBody Modeling System

ANYBODY Modeling System



Model Repository





How to get the new version





What is new?







New in the Modeling System...

- New system for model plugins
- Built-in Python distribution



Active Tools: Main.HumanModel: Configuration

- New toolbar with plugins
- Belongs to the model
- Plugins are small Python applications

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New Metabolism models

- What is it? -> A way to sum the energy expenditure Umberger et al. 2003¹ and 2010²
- Two new classes :
 - o AnyMetabModelUo AnyMetabModelB
- Studies may specify a default **AnyMetabModel**
 - or controlled by individual muscles

Work in progress... Ready for academia and researchers

Contact us! If this is your research area...

• Bhargava et al. 2004³

¹Umberger, B. R., Gerritsen, K. G., & Martin, P. E. (2003). A model of human muscle energy expenditure. *Computer methods in biomechanics and biomedical engineering*, *6*(2), 99-111.

² Umberger, B. R. (2010). Stance and swing phase costs in human walking. *Journal of the Royal Society Interface*, 7(50), 1329-1340.

³ Bhargava, L. J., Pandy, M. G., & Anderson, F. C. (2004). A phenomenological model for estimating metabolic energy consumption in muscle contraction. *Journal of Biomechanics*, *37*(1), 81-88.



Other improvements

Multi selection in model tree



Improved operation control



Model Repository

- Updated body models
 - New deltoid implementation
 - New scapula-thorax contact mechanism.
 - Many improvements and fixes
- New BodyModel configuration plugin
- New model examples
 - Knee simulator
 - Standing model template
 - Standing posture prediction model





How do I get the new Model Repository?





What is new?

Caution: The default leg model has changed in AMMR 2.2 (from TLEM1 to TLEM2). To force the old leg model use: **#define BM_LEG_MODEL _LEG_MODEL_TLEM1_**



anyscript.org/ammr-doc





Shoulder improvements

- New deltoid wrapping implementation
 - The work of Marta Strzelczak from ETS in Montreal [Strzelczak et al. (2018)]
 - Old implementation can be enabled with:

#define BM_ARM_DELTOID_WRAPPING OFF

- Rhythm to control Sterno clavicular axial rotation
- New scapula-thorax kinematics
 - Still testing -> must be enabled explicitly.
 - Solves problem when ribs becomes individual segments.

#define BM_ARM_THORAX_SCAPULA_CONTACT _MULTIPLE_POINT_CONTACT_



Strzelczak, M., Lund, M. E., Sins, L., Mickael, B. & Hagemeister, N. A new wrapping approach for the deltoid muscle modelling. in The Proceedings of the 20th Biennial Meeting of theCanadian Society for Biomechanics (2018).



BodyModel Configuration plugin

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HumanModel	<pre>{ // BodyModel configuration: #include "Model/BodyModelConfiguration.any" }</pre>	Classes
	<pre>// Include the Human model from ANMR #include "<anybody_path_body>\HumanModel.any" // Define your models posture or movement</anybody_path_body></pre>	Globals
Information • 4 × Main	<pre>#include "Model(Mannequin.any" // Compose the model used by the study AnyFolder Model = {</pre>	
AnyMainFolder	<pre>// Center of Mass (COM) position in the ground YZ plane * </pre>	
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New Model Examples:

anyscript.org/ammr-doc





Standing Model

Knee Simulator Model



Posture Prediction Model



Updated Standing Model

Posture controlled by soft Mannequin drivers

Center of Mass balance driver

// Center of Mass (COM) position
// COM balance driver can be excluded with:
// #define EXCLUDE_COM_BALANCE_DRIVERS
AnyVector CenterOfMassXZ = {0,0};



Easy to configure

Easy control of foot position

// Positioning of the right and left feet. // Ground-foot constraints can be excluded with: // #define EXCLUDE_FOOT_CONSTRAINTS Environment.GlobalRef.RightFootPrint = { AnyVec3 HeelPosition = {-0.08, 0, 0.14}; AnyVec3 ToeDirection = {1, 0, 0.1}; };

Full Ground reaction Force Prediction



New Knee simulator example

Long Run Time





New Standing posture prediction

- Predicts posture based on external loads
- Fixed object weight or force vector

AnyVar ObjectWeight = 0;

#define LoadInRightHand 1
#define LoadInLeftHand 1

- Load model, click/drag widgets, release to run analysis:
 - Minimize joint torques
 - Balance drivers (keep CoP within foot stance area)



* Please note the speed of the video was increased for viewing purposes.



What can you expect in 2019?

Updated Glasgow-Maastricht Foot Model with MoCap





Moving axis knee Addon





Teaser: Moving-Axis Knee model



Contents lists available at ScienceDirect Journal of Biomechanics journal homepage: www.elsevier.com/locate/jbiomech www.JBiomech.com



Development and validation of a subject-specific moving-axis tibiofemoral joint model using MRI and EOS imaging during a quasi-static lunge

C.M. Dzialo^{a,*}, P.H. Pedersen^b, C.W. Simonsen^c, K.K. Jensen^c, M. de Zee^d, M.S. Andersen^a

¹Department of Materials and Production, Adhorg University, Filiperstra2de 16, DK-3220 Adhorg, Demark ¹Department of Orchopedic Surgery, Adhorg University Hospital, Hohrovej 18-22, DK-9000 Adhorg, Demarak ¹Department of Radiology, Adhorg, University Hospital, Hohrovej 18-22, DK-9000 Adhorg, Demarak ¹Department of Health Science and Technology, Adhorg University, Fredrik Bogirs V/T DK-8220 Adhorg, Demarak //---Insert the following before <ANYMOCAP_MODEL>-----// Define right/left/both knee joints
#define BM_JOINT_TYPE_KNEE_RIGHT _JOINT_TYPE_USERDEFINED_
#define BM_JOINT_TYPE_KNEE_LEFT _JOINT_TYPE_USERDEFINED_











www.anybodytech.com

• Events, dates, publication list, ...

www.anyscript.org

• Wiki, Forum, Repositories

Events:

Now: ICRA 2019, Montreal, Canada

23-24 May: Seminar - From Mimics segmentation to MSM modeling

28 Jul: TGCS 2019 – ISB satellite conference Workshop on knee osteoarthritis and knee cartilage mechanic

31 Jul- 4 Aug: International Socienty of Biomechanics 2019 - Calgary, Canda.

Meet us? Send email to sales@anybodytech.com





Time for questions:



